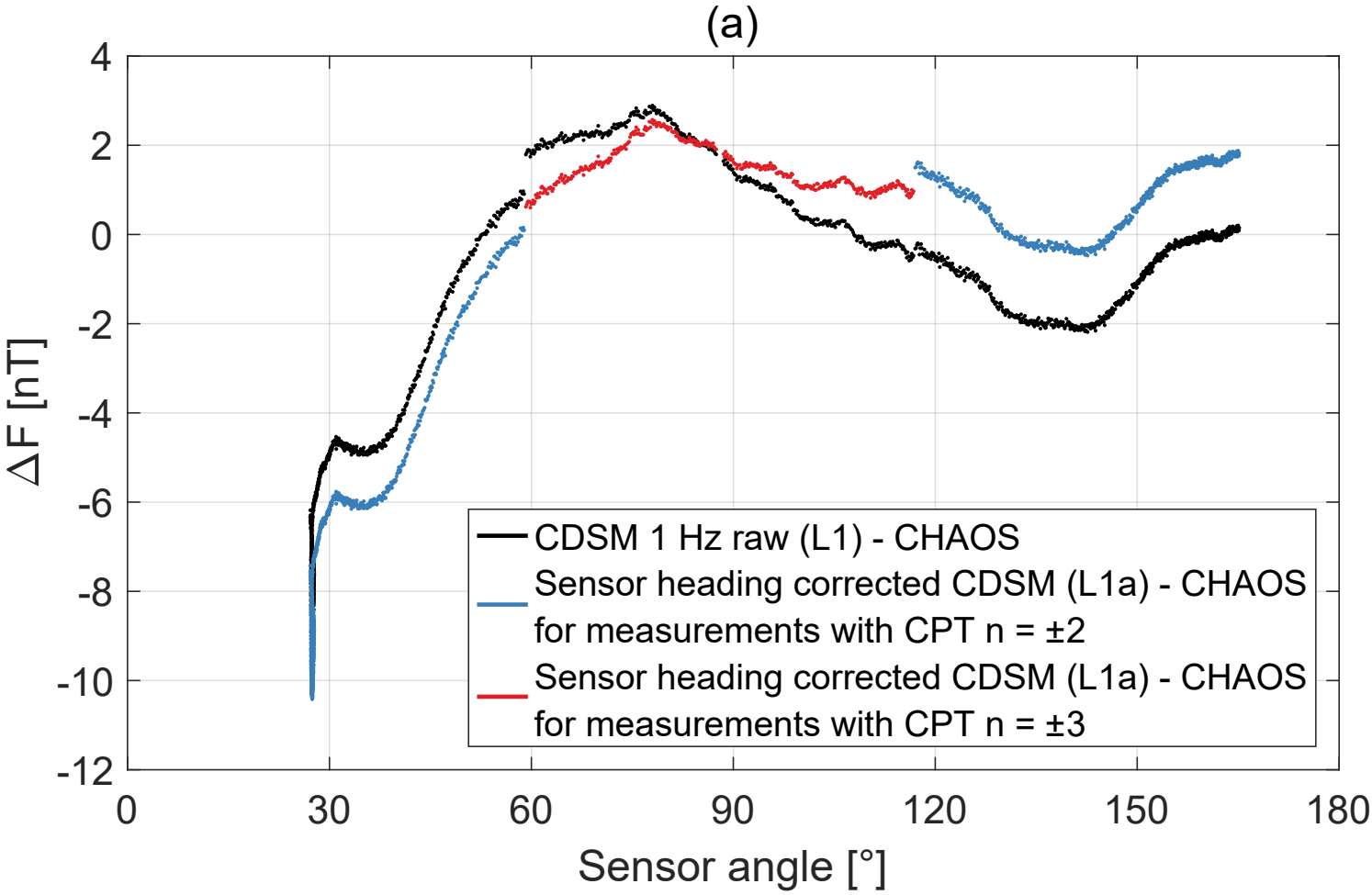
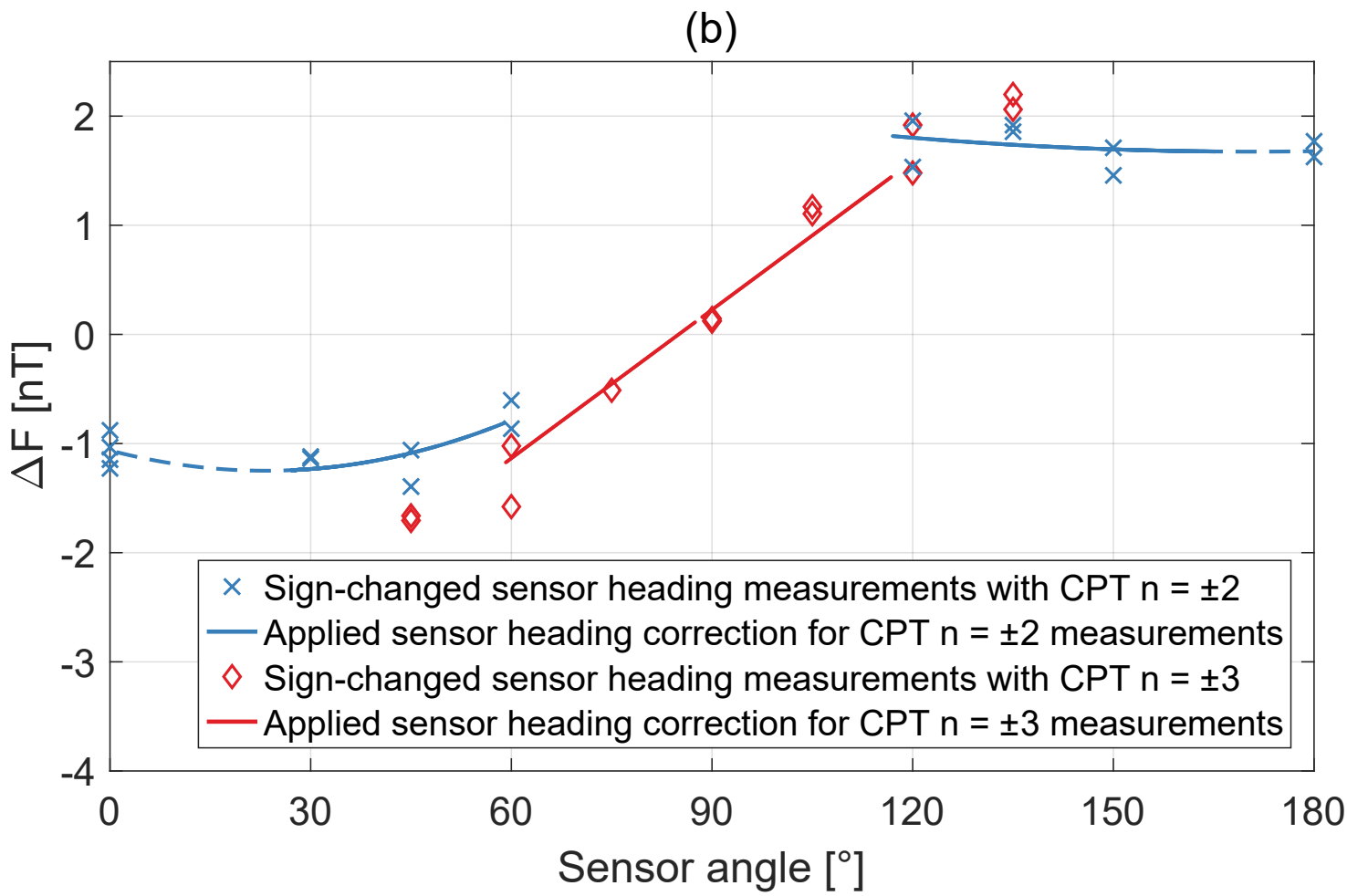

(a)
ΔF [nT]
Sensor angle [°]
CDSM 1 Hz raw (L1) - CHAOS
Sensor heading corrected CDSM (L1a) - CHAOS for measurements with CPT n = ±2
Sensor heading corrected CDSM (L1a) - CHAOS for measurements with CPT n = ±3


(b)
ΔF [nT]
Sensor angle [°]
Sign-changed sensor heading measurements with CPT n = ±2
Applied sensor heading correction for CPT n = ±2 measurements
Sign-changed sensor heading measurements with CPT n = ±3
Applied sensor heading correction for CPT n = ±3 measurements