Continuous In Situ Measurement of Dissolved Methane in Lake Kivu Using a Membrane Inlet Laser Spectrometer

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Abstract. We report the first high resolution continuous profile of dissolved methane in the shallow water of Lake Kivu, Rwanda. The measurements were performed using an in situ dissolved gas sensor, called Sub-Ocean, based on a patented membrane based extraction technique coupled with a highly sensitive optical spectrometer. The sensor was originally designed for ocean settings, but both the spectrometer and the extraction system were modified to extend the dynamical range up to six orders of magnitude with respect to the original prototype (from nmol L^{-1} to mmol L^{-1} detection) to fit the range of concentrations at Lake Kivu. The accuracy of the instrument was estimated to ±22% (2σ) from the standard deviation of eight profiles at 80 m of depth, corresponding to ±112 µBar of CH_4 in water or ±160 nmol L^{-1} at 25°C and 1 atm. The instrument was able to continuously profile the top 150 m of the water column within only 25 min. The maximum observed mixing ratio of CH_4 in the gas phase concentration was 77% at 150 m depth, which at this depth and thermal condition of the lake, corresponds to 3.5 mmol L^{-1}. Deeper down, dissolved CH_4 concentrations were too large for the methane absorption spectrum to be correctly retrieved. Results are in good agreement with discrete in situ measurements conducted with the commercial HydroC sensor. This fast profiling feature is highly profitable to study the transport, production and consumption of CH_4 and other dissolved gases in aquatic systems. While the sensor is well adapted for investigating most of environments with concentration of CH_4 up to few mmol L^{-1}, the spectrometer could be replaced with a less sensitive analytical technique possibly including simultaneous detection of dissolved CO_2 and total dissolved gas pressure for settings with very high concentrations of CH_4, such as the bottom waters of Lake Kivu.

1 Introduction

Methane is the second most important greenhouse gas contributing to the anthropogenic radiative forcing of the atmosphere and its atmospheric content raised by 2.5 times since the Industrial age. During the last decades, significant efforts have been made to better estimate methane contributions of natural and anthropogenic sources to the global atmospheric budget. The development of more advanced techniques allowed the recognition of a larger number of sources which, coupled

with the improvements in the modelling, led to continuous rectifications of this budget (Hamdan and Wickland, 2016). In the last three decades, natural sources contribute for ~35-50% of the total global methane emissions and freshwater constitute one of the largest incomes after natural wetland and together with geological sources (including seafloor). This highlights the importance and urgency for a better inventory of the sources of CH_4, and reduce the uncertainties of the contributions of aquatic

35   systems (lakes, rivers, estuaries, costal seas and open ocean) (Ciais et al., 2013). For this, a better understanding of the processes of production, transport, and transformation are needed and fast response instruments for in situ dissolved gases measurements and dynamic profiling are key tools.

      In this work, a fast response prototype instrument was deployed for the first time at Lake Kivu, located in East Africa at the border between Rwanda and the Democratic Republic of the Congo. The meromictic character of this lake, defined by a

40   strong stratification of the water, makes deep water strongly decoupled from surface water because of their difference in density (Schmid and Wüest, 2012) and therefore very different in composition. The upper tens of meters (ranging from 65 to 25 m depending on seasons) correspond to the oxic zone, with life (fishes, algae and bacteria) while deeper waters are anoxic and contain large amount of dissolved carbon dioxide (CO_2) and methane (CH_4), with the strongest chemocline situated at 250 m of depth (Schmid et al., 2005). Since 1935, several measurement campaigns have been carried out, aiming at quantifying the amount

45   of dissolved CH_4 and CO_2 present in the lake (e.g. (Degens et al., 1973; Pasche et al., 2011; Schmitz and Kufferath, 1955; Tassi et al., 2009; Tietze et al., 1980)). On the one hand, the presence of those gases constitute a risk of catastrophic event such as a gas eruption, which in the past already occurred in other gas-rich lakes (e.g. in 1984 at Lake Monoun and in 1986 at Lake Nyos in Cameroon (Kling et al., 1987; Kusakabe, 2017; Sigurdsson et al., 1987)). On the other hand, dissolved CH_4 represents a potentially important energy resource. Methane extraction would allow to compensate further accumulation of gas at the bottom of the Lake

50   and therefore preventing the possibility of a gas eruption. From this field campaign, the maximum total dissolved gas pressure (TDGP) was estimated to be 50±7 % of the hydrostatic pressure at 320 m of depth (Bärenbold et al., 2019; Schmid et al., 2019). Meanwhile, extraction has to be performed without destabilizing the stratification of the lake or altering its ecosystem. Regarding the stability of the lake, in 2005 Schmid et al. (Schmid et al., 2005) raised the possibility that dissolved CH_4 in the lake was increasing with a rate of ~0.5 % per year, with consistent repercussion on the safety of the surrounding population. However,

55   from the work of Pasche et al. (2011) as well as the results from this recent field campaign, the hypothesis of a fast increase is today excluded, and the temporal variability appears to be slower than previously expected (Bärenbold et al., 2019; Boehrer et al., 2019; Schmid et al., 2019). In the future, regular monitoring of the lake is required to estimate the CH_4 and CO_2 budgets as well as their temporal variability, using reliable, fast and easy to use techniques. For a more precise estimation of the dissolved gas content, inter-comparison between different sensors and methods is required, as conducted and presented in this work and in

60   the even more comprehensive results from the entire inter-comparison campaign (Bärenbold et al., 2019; Boehrer et al., 2019; Schmid et al., 2019). A fast response sensor as the one proposed in this work could also be highly profitable for estimating the methane fluxes from the water surface and their spatial and seasonal variabilities.

      The development of the Sub-Ocean sensor grew out of a project for measuring the composition of air bubbles in-situ in ice sheets (Alemany et al., 2014; Grilli et al., 2014). After a first test in the Mediterranean Sea in 2014 with a different prototype but

based on the same principle (Grilli et al., 2018), the sensor described and deployed here was developed. In October 2015 it was deployed over a hydrate degassing zone west of Svalbard, highlighting for the first time high variability of dissolved CH_4 near the seabed together with a strong diffusivity most probably induced by the di-phasic medium generated by the gas flares (Jansson et al., 2019). In this work we report a successful deployment of the Sub-Ocean sensor in a very different setting, highlighting the reliability and adaptability of the technique to different aquatic environments. Advantages and drawbacks of the technique are highlighted in the discussion section. Two other research groups participated to the inter-comparison campaign using different methods: water sampling followed by laboratory gas chromatography analysis (Boehrer et al., 2019) and on-line water pumping followed by on-site mass spectrometry analysis (Brennwald et al., 2016). These results are not reported here as they focused on the concentrations in the deep waters (Bärenbold et al., 2019; Schmid et al., 2019).

Methane concentrations at Lake Kivu spans from few tens of nmol L^{-1} at the surface up to ~18 mmol L^{-1} at the bottom. Other lakes of the same kind have different concentration ranges. For instance, Lake Pavin in France and Lake Vollert-Sued in Germany both reach concentrations up to few mmol L^{-1} (Horn et al., 2017; Lopes et al., 2011) making our probe in its current status well suitable for acquiring continuous full vertical profiles in these lakes.

2 Materials and Methods

2.1 The Sub-Ocean Instrument

The optical instrument used in this study is based on the OFCEAS technique (optical feedback cavity enhanced absorption spectroscopy) (Morville et al., 2003, 2014) developed for trace gas sensing. The dissolved air from the extraction unit (Figure 1) is continuously pumped toward the optical cavity of the spectrometer. The internal volume of the cell is less than 20 cm^3 and provides sample residence times < 30 sec for optimal running conditions (compromise between the cell pressure and the total gas flow).

Extraction of dissolved gases from water is performed using a silicon polydimethyl silicone (PDMS) membrane. The extraction technique does not rely on gas equilibration across the membrane but, in order to achieve fast response, the dry side of the membrane is maintained at low pressure while continuously flushing it with dry zero air (Triest et al., 2017). The pressure at the membrane dry side controls the total flow of dry and wet air through the membrane, and the system is designed to keep this pressure constant. While the spectrometer operates at about 20 mbar, the pressure at the dry side of the membrane is maintained at about 30 mbar.

A full description of the in situ membrane inlet laser spectrometer instrument (Sub-Ocean), together with the experimental setup used for laboratory calibrations can be found in (Grilli et al., 2018). In order to adapt the instrument to the high concentrations of dissolved CH_4 expected in Lake Kivu, the absorption spectrum of the optical spectrometer was set away from the strong CH_4 rotational-vibrational transitions, more precisely at 2238.5 nm, where concentrations inside the optical cavity may reach up to 1.5 - 2 % of CH_4 in air before optical saturation (equivalent to an absorption 10^{-5} - 10^{-6} cm^{-1}). Above this absorption, the transmission signal at the maximum of the peak of absorption becomes too weak and the optical feedback

to the laser, required with the OFCEAS optical technique, not strong enough to lock the laser frequency for a period of time close to the cavity free spectral range. This leads to narrower cavity modes and to a failure in retrieving the absorption feature correctly. A stainless-steel membrane block (MB) was equipped with two 10 μm thick polydimethylsiloxane (PDMS) membranes of 56 mm diameter mounted face-to-face. The thin-film membranes were mounted on porous bronze frits of 3 mm of thickness (Poral, grade 20), providing mechanical strength for the membrane under high hydrostatic pressure. A schematic of the membrane block can be found in the supplementary information of Grilli et al., 2018.For this campaign, in order to increase the dynamic range of the measurements, one of the two membranes was replaced with a gas-tight Teflon film. This increased the dilution factor by decreasing the flow of the permeating gas with respect to water vapor and carrier gas flow, but degrades the precision of the measurements due to the low dry gas flow through the membrane. A picture of the instrument and the assembly taken during the campaign is shown in Figure 2. The main (central) pressure tube (140-cm long, 28-cm diameter) is mounted on a metal frame. The membrane block at the bottom is connected with a submersible water pump (Sea-Bird Electronics, SBE 5T) providing a flow of 0.8 L min^{-1} along the membrane. A 1 L carrier gas (CG) tank containing dry zero air at a pressure between 2 and 40 bar depending on the suitable autonomy is attached on the frame and connected to the instrument via a 1/8" stainless-steel tube. A subsea battery (Seacell, STR) was mounted on the metal frame, providing up to 12 hours of continuous operation. An independent CTD (Sea & Sun Marine Tech, CTD-60) was also attached to the frame for depth, temperature, conductivity and dissolved oxygen measurements. For an operation where the instrument is powered through an electromechanical cable the autonomy will be limited by the storage of the dry gas inside the instrument housing. For fast response measurements at maximum carrier gas flow of 6 ml min^{-1} this will correspond to 24 h autonomy, whereas without the use of carrier gas the autonomy will stretch to 90 days since most of the gas flow will be composed of water vapor that is trapped before the vacuum pump by the silica gel dryer (however, the long-term deployment may be limited by the capability of the silica gel).

The embedded spectrometer is continuously measuring the gas composition at 10 Hz, while the response time of the sensor during the campaign, expressed as τ_{90}, was ~10 sec. At a lowering speed of ~6 m min^{-1}, this corresponds to a vertical resolution of 1 m.From the composition of the dissolved gas the instrument can give an indirect estimation of the amount of N_2. This requires to know: TDGP, pCO_2 and pO_2 which were not measured by the Sub-Ocean probe and relies on other sensors. The partial pressure of N_2 can then be estimated as $pN_2 = TDGP - pCH_4 - pCO_2 - pO_2$.

2.2 The HydroC-CH$_4$ commercial instrument

In situ discrete measurements of dissolved CH_4 at five different depths along the upper 150 m of the water column were performed using a commercial equilibrium-based underwater sensor, the HydroC HP system (Contros). The dissolved gas diffuses from the liquid through a thin film composite membrane into an internal gas cell. Therein, the total dissolved gas pressure and the partial pressure of CH_4 gas are measured by a pressure sensor and a non-dispersive infrared spectrometer, respectively. The HydroC CH$_4$ HP sensor is similar to the HydroC CO_2 sensor presented in (Fietzek et al., 2014), except for

the absence of an internal zeroing system and a CH_4-specific fixed narrow-band spectral filter from 3.3-3.4 µm. The sensor was calibrated in October 2012 and November 2015 by the manufacturer. The calibrations were made using a specially designed pressure chamber with fresh water brought to pressure using compressed target gas. Three standard gas mixtures of CO_2, CH_4 and N_2 (100 % pressure N_2; 50 % pressure CH_4 and 50 % pressure CO_2; 100 % pressure CH_4) were used to equilibrate the water volume along a gas pressure gradient (5-6 points) from 1 up to 30 bars and partial pressures of CH_4 from 0.5 to 18 bars. The calibration results showed the absence of a significant drift of the sensor (< 3 % within the Lake Kivu gas concentration range) between the October 2012 and November 2015 calibrations. Also, several CH_4 profiles were carried out in Lake Kivu from 2016 to 2018 using the HydroC CH_4 HP sensor and the repeatability of the observed CH_4 partial pressures was 3.8 % (2σ) below the main density gradient. However, the calibration curve as a function of the methane concentration was determined by using three points (0, 50 and 100% CH_4), and because of the nonlinear behavior of the detection system, a systematic error could be present, but it should not exceed 10 % (manufacturer personal comm.).

The HydroC-CH_4 system was mounted on a SeaBird 19plus V2 SeaCAT CTD profiler equipped with a SBE 43 Dissolved Oxygen sensor and a SBE 18 pH sensor. Calibrations of the SeaBird sensors were performed following manufacturer instructions. Water circulation in front of the HydroC membrane was provided by a SeaBird 5T pump, ensuring a continuous and homogeneous water flow to the membrane. A zero calibration of the HydroC CH_4 HP system was made daily before each deployment using surface waters. The sampling rate was 1 Hz. The steady-state of the sensor was generally reached within 40 minutes and real-time data communication using an electromechanical cable allowed to adjust the waiting time at each depth accordingly. In all cases, the waiting time for each depth never exceeded 1 hour. The retained partial pressure of CH_4 is the average for the last 5 min of the equilibration curve.

2.3 Calculation of dissolved CH_4

Both the SubOcean and the HydroC HP sensors measures CH_4 in the gas phase, and raw data are expressed as the concentration of CH_4 with respect to the total amount of dry gas permeating the membrane. For the MILS system, the concentration of CH_4 in the dry gas downstream from the membrane $[CH_4]'_g$ can be expressed with respect to the expected concentration of the gas in the headspace which would be in equilibrium with the water sample, $[CH_4]_g$. In eq. 1, Pr are the membrane permeability coefficients for CH_4 and X (N_2, O_2 and CO_2) reported in Robb (1968), but corrected for their temperature and salinity dependency.

$$[CH_4]'_g = \frac{Pr_{CH_4} \cdot [CH_4]_g}{\sum Pr_X \cdot [X]_g} \quad , \tag{1}$$

Concentrations, $[CH_4]$, $[X]$ are expressed as mixing ratios. Measuring the concentration of water vapor $[H_2O]_g$ is required in order to retrieve the dissolved CH_4 concentration, $[CH_4]_{dissolved}$, since water vapor flow will cause dilution of the measured dry

gas mixture (as well as the carrier gas flow). This measurement is performed by the OFCEAS spectrometer embedded in the Sub-Ocean probe, simultaneously with the CH_4 measurement. Precision on the water vapor concentration was $\pm$ 0.6 % (2σ). $[CH_4]_{dissolved}$ is then calculated from the following equation:

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$$[CH_4]'_{dissolved} = \frac{[CH_4]'_g \times f_t}{f_t - f_{CG} - (f_t \times [H_2O]_g)} \times \frac{1}{m_{eff}},$$

(2)

where $[CH_4]'_g$ represents the methane mixing ratio measured by the optical spectrometer, f_t and f_{CG} are the total- and carrier-gas flow (ml min^{-1}), respectively, and $[H_2O]_g$ corresponds to the mixing ratio of water permeating through the membrane. The

170 denominator term $(f_t - f_{CG} - (f_t \times [H_2O]_g))$ corresponds to the dry flow permeating the membrane. m_{eff} represents the enrichment factor due to the membrane and corresponds to the quantity $\frac{Pr_{CH_4}}{\sum Pr_x \cdot [X]_g}$ in eq. 1. Its dependency with temperature and salinity is calculated by running calibrations under various conditions (Grilli et al., 2018). From our calibration, a m_{eff} of 2.84 $\pm$ 0.11 for fresh water at 25°C and 1.2 bar was calculated. This is in agreement with an expected value of 2.76 calculated from the permeation coefficients reported by Robb (1968).

175 As reported in eq. 1 above, this technique requires to know the main composition of the dissolved gas, in order to account for the different permeation coefficients of the species through the silicon membrane. This does not represent a problem for most of the ocean and lake settings, where the gas mixture is mainly composed of nitrogen and oxygen, but it requires a more complex analysis for a setting such as Lake Kivu. For the data analysis we assumed a bulk gas mainly composed of N_2, O_2, CO_2 and CH_4. H_2S is only present in bottom water and in lower amount with respect to CO_2 and CH_4, and was therefore

180 neglected here. Oxygen concentrations were calculated from the CTD measurements and converted into partial pressure using equation 19 from Sander 2015 (using H^{cp} of 1.25 $\times$ 10^{-5}mol m^{-3} Pa^{-1} and dln(H^{cp})/d(1/T) of 1500 K) (Sander, 2015).

As mentioned above, concentrations reported so far are expressed in mixing ratio with respect to the total dissolved gas pressure TDGP. Therefore, by knowing the TDGP, a value of partial pressure, pCH_4, can be retrieved which is then converted into dissolved methane concentrations, C_{CH4}, expressed in mol per liter of water. This conversion is performed by taking into

185 account the solubility of the gas in water under given physical conditions as well as its fugacity. The procedure has been previously described in a scientific report (Schmid et al., 2019). C_{CH4} is related to the pCH_4 through the following equation:

$$C_{CH4} = K(T, S, P)\, pCH_4\, \varphi_{CH4}(T, P) \ ,$$

(3)

190 where φ_{CH4} is the fugacity coefficient, i.e. the ratio between the fugacity of a gas and its partial pressure, which is a function of temperature T, pressure P and gas composition, and K is the solubility coefficient, i.e. the ratio between the dissolved concentration of a gas and its fugacity. The solubility coefficient K (mol L^{-1} atm^{-1}) of CH_4 as a function of temperature T (K) and salinity S (g/kg) is calculated using the following equation:

$$ln(K) = A_1 + A_2(100/T) + A_3 \ln(T/100) + S[B_1 + B_2(T/100) + B_3(T/100)^2] \ , \tag{4}$$

The parameters in eq. 4 are from Wiesenburg and Guinasso (1979) (Wiesenburg and Guinasso, 1979).

The solubility coefficients need to be corrected for the local pressure P (bar) at the sampling depth (sum of hydrostatic pressure plus atmospheric pressure), using the following equation (Weiss, 1974):

$$K(P) = Ke^{\left[\frac{(1-P)\,v_{CH4}}{RT}\right]} \ , \tag{5}$$

where R = 83.1446cm^3 bar K^{-1} mol^{-1} is the gas constant, and v_{CH4} is the partial molar volume (cm^3 mol^{-1}) of CH$_4$ calculated from Rettich et al., 1981 (Rettich et al., 1981).

The fugacity coefficients were calculated using the methods described by Ziabakhsh-Ganji and Kooi (Ziabakhsh-Ganji and Kooi, 2012). A Maple script was provided by Z. Ziabakhsh-Ganji, which was transcribed to Matlab code by M. Schmid (Schmid et al., 2019). The script calculates, among other things, the fugacity coefficients for CO$_2$ and CH$_4$, including the interactions between both gases.

2.4 The Lake and the field campaign

Lake Kivu [2.50°S - 1.59°S ; 29.37°E - 28.83°E] located at 1460 m above sea level, has a surface of 2 700 km^2 (of which 2385 km^2 represents the water covering) and a maximum depth of ~485 m. The measurement campaign took place from 9th to 13th March 2018 at ~6 km from Goma and ~5 km from Gisenyi/Rubavu at the Northern shore of the lake (1.74087°S - 29.22602°E) and nearby a permanent platform with water depth of 410 m. During the campaign other types of measurements of dissolved methane and carbon dioxide were performed. The research team from Eawag (Switzerland) analyzed pumped water on the platform using a field mass spectrometer instrument (Brennwald et al., 2016), while a second team from UFZ (Germany) sampled water from a boat and measured the samples by head-space equilibration and gas chromatography (GC) analysis at the Lake Kivu Monitoring Program (LKMP) laboratory in Rubavu (Boehrer et al., 2019). The Sub-Ocean sensor was deployed from a research boat during three days of the campaign: 10th, 12th and 13th of March, with a total of eight continuous profiles. Measurements with the commercial HydroC HP sensor were conducted during the campaign and on May 8th -11th at the same location as the Sub-Ocean measurements.

3 Results and Discussions

In Figure 4 an example of a consecutive downward and upward profile of dissolved CH$_4$ measured by the Sub-Ocean sensor is reported. CH$_4$ concentrations are expressed as mixing ratio with respect to the total dissolved gas. The sensor was lowered at a speed of ~6 m/min, reaching 100 m depth in only 18 min. The response time of the sensor during the campaign

expressed as τ_{90} was ~10 sec, which corresponds to a vertical resolution of 1 m. On the right-hand side, dissolved CH_4 is plotted against depth, showing the reproducibility of the sensor during descent and ascent.

A total of eight continuous profiles (downward and upward) were obtained with the Sub-ocean instrument during the campaign. They are reported in Figure 5 together with dissolved CO_2, CTD data (temperature, conductivity and dissolved oxygen) and total dissolved gas pressure (TDGP). For the measurement of CH_4 only one of the eight profiles reached 150 m, while the others are shallower, only covering the upper 100 m of depth. The accuracy of the measurement was estimated at 80 m depth, where water mass is well stratified. At this depth, an average concentration of 35.5 ± 7.8%, corresponding to 508.3 ± 112 mbar of partial pressure and 0.71 ± 0.16 mmol L^{-1} of CH_4 was calculated, leading to a repeatability of ± 22% (2σ). This relatively large standard deviation can be explained by the large uncertainty in determining the total flow of dry gas permeating the membrane. The value is in agreement with previously observed performances, where an error propagation of ±12% (2σ) was calculated using two semipermeable membranes (Grilli et al., 2018). The use of only one membrane allowed to further increase the dynamic range of the sensor by diluting the dry gas permeating the membrane. However, in this condition, a dry gas flow of only ~0.065 cm^3 STP/min is delivered by the extraction system. The large uncertainty on this dry flow measurement directly affects the accuracy on the retrieved concentration. The uncertainty represented by the grey lines in Figure 6 represents the measured variability over the eights vertical profiles from 0 to 80 m, and was fixed to ± 22% at larger depths . The CO_2 data are from Schmid et al. (2005) and are calculated from alkalinity and pH measurements (Schmid et al., 2005). TDGP are discrete measurements at seven different depths measured with the HydroC HP sensor which have been interpolated to match the depth resolution of the Sub-ocean data. Nitrogen, N_2, mixing ratio was retrieved assuming that the main gas is composed by N_2, CO_2, CH_4, and O_2 (pN_2 = TDGP – pCH_4 - pCO_2 - pO_2).

The molar concentrations as a function of depth for the average continuous profile recorded by the Sub-Ocean sensor and for the discrete measurements obtained with the HydroC HP sensor are reported in Figure 6. A good agreement between the two independent measurements is observed. The measurements were obtained during the same field campaign at the measurement site location near Goma (the two vessels were a few hundred meters away from each other). However, the measurements were not performed simultaneously. In the graph, results from previous campaigns are also reported. Data from the University of Liege obtained during a long term monitoring of the lake are reported in orange. Data were collected from June 2011 to August 2014 at different periods of the year (both dry and rainy seasons) and at different locations (northern and south basin) (Roland et al., 2017, 2018). The large variability of these data is reported by the orange lines (Figure 6) defining the 3σ distribution of the data. Data from the works of Pasche et al. 2011 and Schmid et al. 2005 are also reported in green and blue, respectively. Data from ULiege and Pasche 2011 were obtained by sampling the water using Niskin bottles and analyzing the dissolved gas in the laboratory by head-space technique. The others (this work and Schmid 2005) are from in situ measurements. From the data, one can see that below 80 m depth, where the TDGP becomes larger than atmospheric pressure (1.4 bar at 80 m, Figure 5), a problem due to degassing of the sample collected on the Niskin bottles was observed, leading to an under-estimation of the dissolved CH_4. Data from Schmid 2005, which are from a commercial Capsum Met sensor (Franatech) and data from the

Contros sensor are a bit lower than the measurements with the Sub-Ocean probe at higher concentrations (and depths), but they still lie within the measurement uncertainties. During the campaign the HydroC HP sensor also showed a good agreement with the other discrete techniques (on site mass spectroscopy and discrete sampling followed by GC analysis) between 150 and 250 m, while at larger depths, the HydroC HP values were lower by ~12% (Schmid et al., 2019). This may be due to a problem of calibration of the sensor, but it requires further investigations to be confirmed. Regarding the Capsum Met sensor, no information about the calibration of the sensor were found, therefore no further discussion can be carried out.

Surface measurements performed by the Sub-Ocean instrument lead to average concentrations of 0.59 ± 0.03 μmol L^{-1} and 0.72 ± 0.14 μmol L^{-1} over the upper 10 and 30 m, respectively. Those values sit at the higher edge of the observed average seasonal concentrations, which span from 0.008 to 11 μmol L^{-1} (Roland et al., 2017, 2018, and more recent unpublished data). Despite the large seasonal and spatial variability, our results are in good agreement with the one from Pasche et al 2011 which were obtained at a similar time of the year but at different locations (May 2006 and 2007 in Kibuye, Gisenyi and Ishungu). A stronger similarity can be found with the dataset from the same location (Gisenyi 2007) in the northern basin. CTD measurements (temperature, conductivity and dissolved oxygen, Sea & Sun Marine Tech, CTD-90M) performed a few months prior to the campaign at the research platform (Figure 7) confirmed a typical behavior of the lake stratigraphy while going from a dry into a rainy season (Roland et al., 2017) and justified therefore the high concentrations measured in this work. The lake was mixed down to at least 50 m depth during the previous dry season, and started to stratify in mid-December, leading to a 25-m depth seasonal thermocline. Below the thermocline, O_2 was rapidly consumed by mineralisation of organic matter and oxidation of reduced compounds (e.g. methane, ammonium) diffusing upward. By the end of February, O_2 supplied at these depths during the previous dry season was completely vanished. Then, on the first-half of March, a mixing event occurred down to about 35 m depth, favoring the mixing between anoxic water (35-25 m depth), enriched in dissolved CH_4, and surface water. From the top 10 m layer temperature profiles reported in Figure 7 one can see that by March 22nd the temperature slope disappeared, supporting the occurrence of the mixing event. Unfortunately, the reasons for this mixing event are still unknown. Meteorological records from December 2017 to March 2018 do not indicate neither high wind speed, low temperature, nor low relative humidity events that could clearly support our observations. Comparing the second half of February to the first half of March, average temperatures decreased by 1°C (from 21.2 to 22.2°C) and average precipitations increased by a factor of two, with peaks up to 7.6 mm of rainfall on March 6th. As reported by Rooney et al., 2018, rain may have a cooling effect on the lake surface by lowering the near-surface air temperature and inducing a convective mixing of the lake surface layer. Further investigations are required to better understand the dynamic of the surface layer of the lake at this period of the year.

This type of fast response sensors could be used to better investigate the fluxes of CH_4 (or other greenhouse gases) from lakes, oceans, rivers and other water reservoirs. In this campaign only a specific location at 5 km from the coast with 410 m of water depth was investigated. The amount of CH_4 at the surface may strongly depend on the water depth i.e. on the distance of the sediment to the surface. A fast sensor could allow to follow the spatial distribution of dissolved gas at the surface for different depths, as well as its variability over the seasons. This would help to better constraint the greenhouse gas emissions in the face of global change (DelSontro et al., 2018).

Beside the advantages of the Sub-Ocean probe to provide in situ, continuous and fast measurements, some drawbacks of the technique can be identified: **i)** the instrument was designed for measuring background concentrations in the oceans (sub-nmol L^{-1}) while Lake Kivu reaches ~18 mmol L^{-1} in bottom waters, thus with eight orders of magnitude difference. Despite the efforts to make the sensor less sensitive, the Sub-Ocean could not measure below 150 m depth, corresponding to a maximum measurable concentration of 3.5 mmol L^{-1}, where absorption becomes too strong for the optical spectrometer at the selected laser frequency. **ii)** In such environment, a good knowledge of the total dissolved gas pressure and of the concentration of dissolved CO_2 are required for a correctly determine the concentration of CH_4. Those parameters were measured during the field campaign, but they are not currently integrated in the sensor. This could be performed in the future by detecting simultaneously CO_2 and CH_4 using the same gas analyzer and by integrating the TDGP measurement or deploying the sensor with an independent TDGP device. It should be noticed that TDGP sensors have response times of a few minutes (e.g. $\tau_{63} = 2$ min for the Mini-TDGP from Pro-Oceanus) which could be a limiting factor with respect to the faster response time of the Sub-Ocean sensor. **iii)** Because a small dry gas flow through the membrane was required (in order to increase the dilution factor), the precision of the measurement was degraded by a factor of two with respect to previous deployments, leading to a ±22% precision. By using a less sensitive gas analyzer, the above drawbacks could be avoided, or at least minimized, making the technique fully suitable for monitoring meromictic lakes with a large range of dissolved CH_4 concentrations.

4 Conclusions

The comparison between different types of measurements confirms the reliability of the fast response membrane extraction system of the Sub-Ocean sensor under more extreme conditions (in terms of dissolved gas content) than ocean settings. Lake Kivu is particularly challenging because of the high amount of dissolved CH_4 and CO_2 as well as their large variability. The gas composition strongly varies across the oxic-anoxic boundary and further down across the different chemoclines, going from a background composed by N_2 and O_2, to another one which sees CH_4 and CO_2 as the main dissolved gases. The Sub-Ocean sensor allowed fast vertical profiles of CH_4 which are in good agreement with the discrete in situ measurements made with the commercial HydroC HP sensor at five different depths. During the campaign the HydroC HP sensor also showed good agreement with the other discrete techniques (on site mass spectroscopy and discrete sampling followed by GC analysis) between 150 and 250 m. At 80 m of depth, no spatial variability of the dissolved gas is expected and we therefore estimate the accuracy of the SubOcean sensor to ±22% (2σ) by comparing the eight independent profiles at this depth. The maximum measurable concentration of dissolved CH_4 was 3.5 mmol L^{-1} at 24°C, 150 m of depth, and TDGP of 2.62 bar, which corresponds to a mixing ratio of 77% with respect to the total dissolved gas.

An average concentration of 0.59 ± 0.03 μmol L^{-1} of CH_4 was found in the 10-m surface layer, which sits at the higher edge of the observed average seasonal concentrations of the lake. The variability of the physical parameters during a period of three months prior the campaign suggests a mixing event of the top 35 m, which can explain the high values measured at the

surface. The causes of this mixing event are however not clear and further investigations will be required to better understad the behavior of the lake while going from the dry into the rainy season.

Such a campaign highlights the advantages of using the Sub-Ocean technology for measuring the dissolved gas content in meromictic lake settings. The technology allows in situ, continuous and fast profiling, important for a long-term monitoring of water resources. The in situ deployment prevents any possible contamination and artefact of the measurement due to water and/or gas sampling and subsequent laboratory analyses. The fast response of the instrument would allow to complete a full vertical profile over 470 m of depth within ~1h 20min, while current techniques of in situ discrete sampling would take more than1h per measured depth. The measurement by this technique has now been proven over a very large dynamic range of seven orders of magnitude, spanning from sub-nmol L^{-1} in open ocean waters to mmol L^{-1} concentrations of dissolved CH_4 and in a context of very different dissolved gas composition and TDGP. The instrument is therefore well suitable for fast profiling on different water reservoirs, and could be further adapted to the entire vertical column of Lake Kivu by using a less sensitive gas analyzer.

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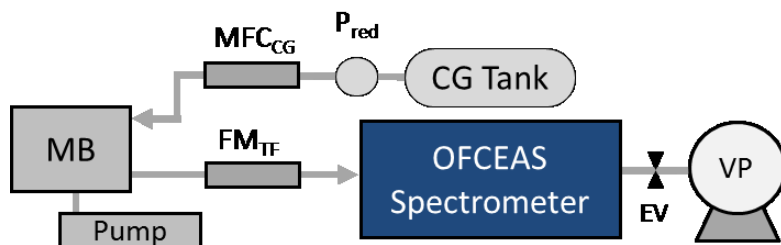
Figure 1. A schematic of the Sub-Ocean sensor. MB is the membrane block where the gas extraction occurs. Water circulates at the membrane using a submersible pump. The carrier gas (CG) flow is controlled by a mass flow controller (MFC_{CG}) and the flowmeter FM_{TF} is used for monitoring the total gas flow. The low pressure on the optical spectrometer is provided by a vacuum pump (VP) and an electronic valve (EV). P_{red} is a pressure reducer.
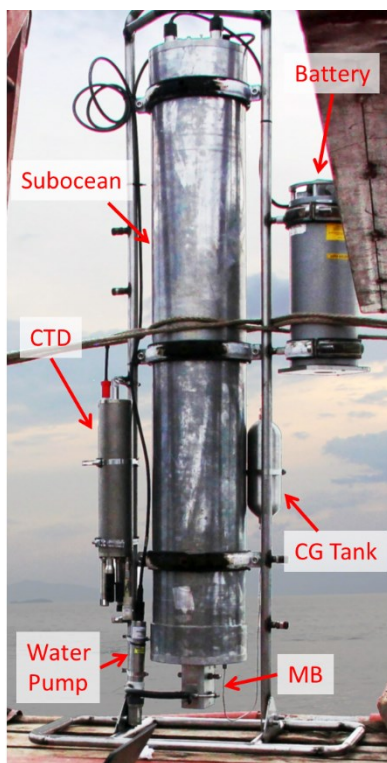

Figure 2. A picture of the Sub-Ocean instrument and the full assembly. The sensor is mounted on a metal frame. The main tube at the center is 150-cm long and 28-cm diameter. The membrane block (MB) at its bottom is connected to the water pump to ensure a constant flow of water against the membrane. The carrier gas (CG) tank is attached to the metal frame and connected with a 1/8" stainless-steel tube at the instrument. An STR battery pack and a CTD sensor were also attached to the metal structure. The total weight of the assembly is 120 kg with about -50 kg of buoyancy.
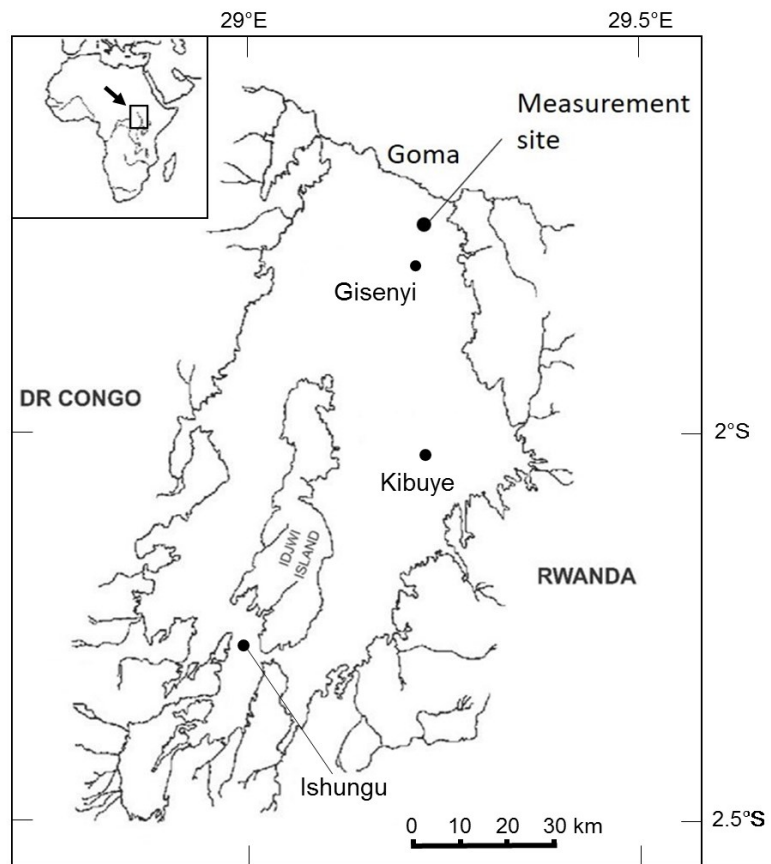
470 **Figure 3**. Map of Lake Kivu showing the location of the measurement site. Locations of previous campaigns mentioned in the discussion part are also reported (named Gisenyi, Kibuye and Ishungu).
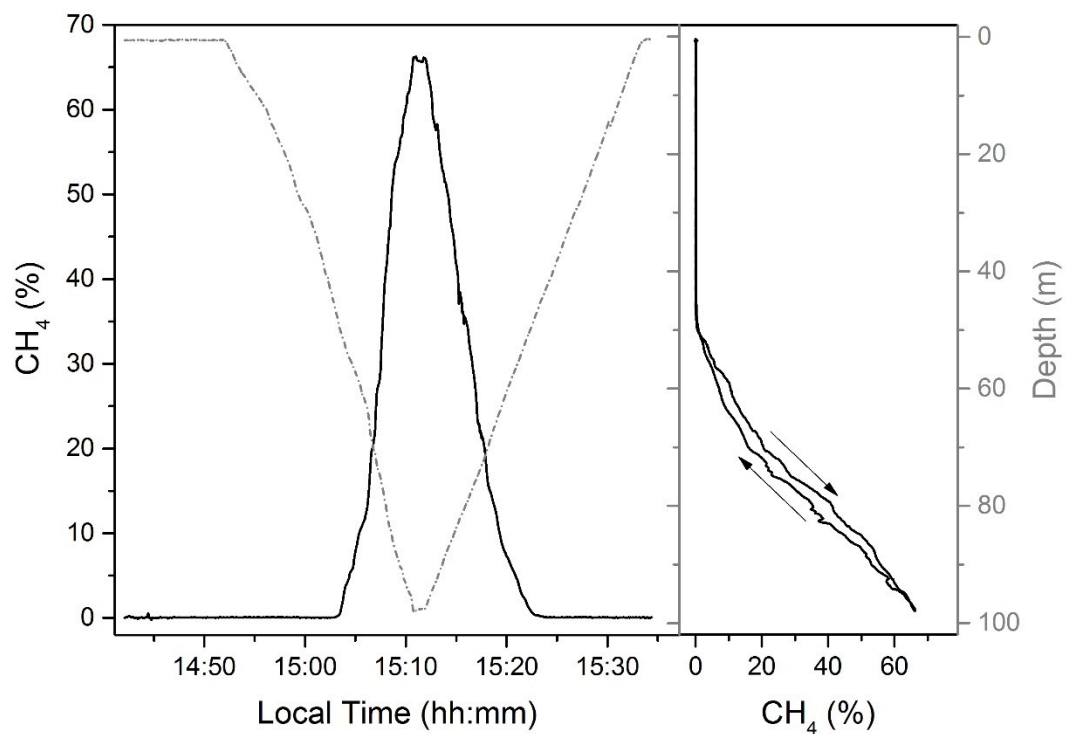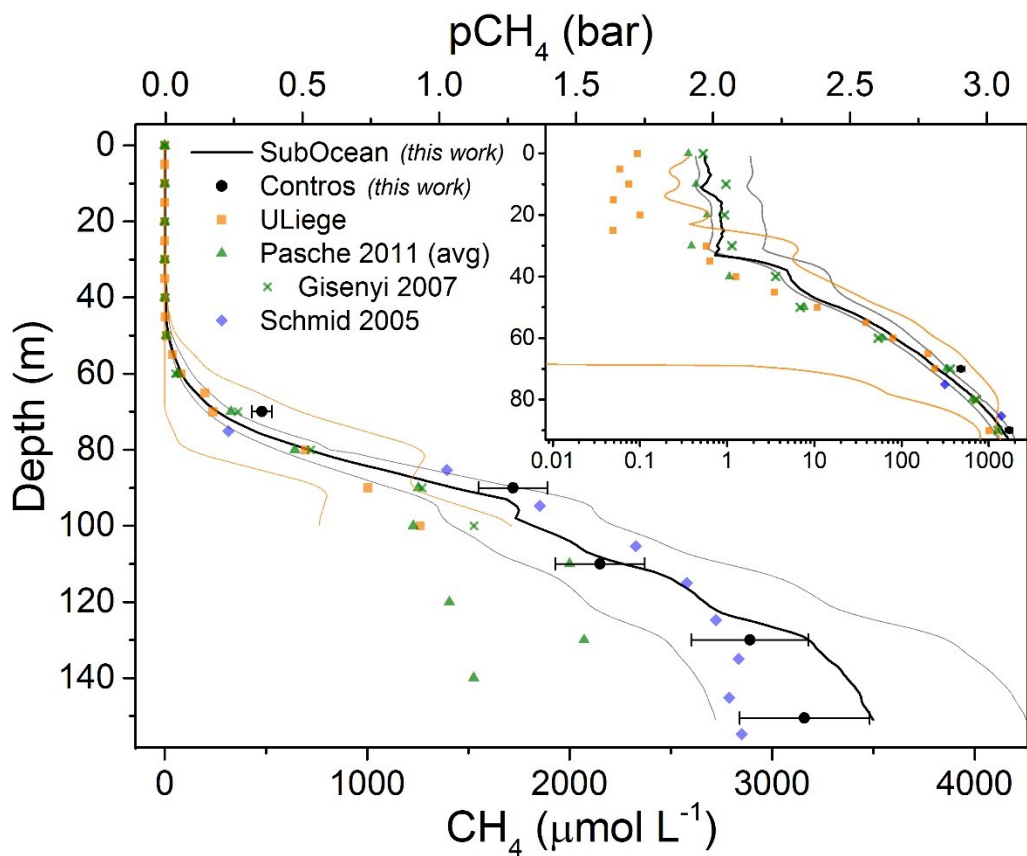
Figure 4. One of the methane continuous profiles recorded by the Sub-Ocean on 10th March 2018. The concentration is expressed as a percentage of CH_4 with respect to the total dissolved gas. The 100 m downward and upward profile was recorded in 42 min. On the right panel the two profiles are superposed, highlighting the reproducibility of the measurement between descent and ascent.
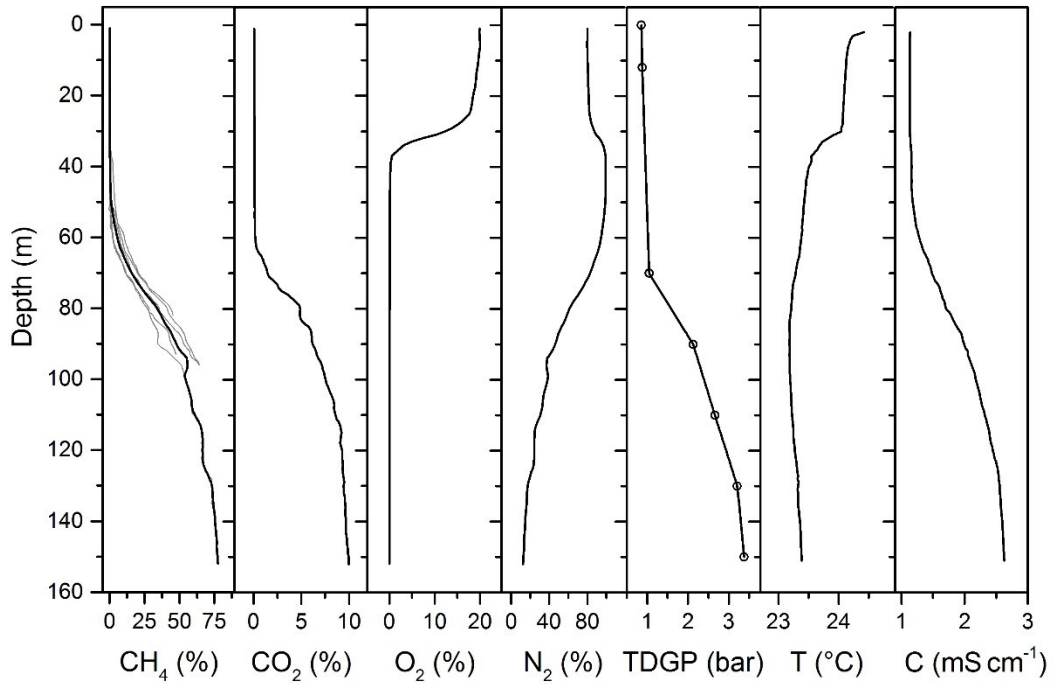
Figure 5. Mixing ratios of individual gas species in the dissolved gas mixture and total dissolved gas pressure. Grey CH_4 lines combine the eight profiles recorded by the Sub-Ocean instrument during the campaign, while the black line is the averaged value. CO_2 data are from (Schmid et al., 2005), O_2 comes from CTD data during the campaign, and N_2 is a concentration profile deduced from the other measurements (TDGP – pCH_4 - pCO_2 - pO_2). The total dissolve gas pressure, TDGP, was measured using the Contros HydroC HP sensor (open circles), the black line is an interpolation of the data. Temperature and electrical conductivity were recorded by the CTD during the deployment.

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Figure 6. Continuous methane profile of the upper 150 m of water depth in Lake Kivu measured by the Sub-Ocean instrument (black line). Grey lines represent the measured variability over the eight continuous profiles estimated between 0 and 80 m depth and fixed to the estimated uncertainty of ± 22 % at larger depths. Black dots are discrete measurements made with the Contros HydroC HP sensor at different depths. Error bars corresponds to the estimated uncertainty of ± 10 %. Orange squares are from the long term monitoring from the University of Liege (Roland et al., 2017, 2018) with the corresponding 3σ variability (orange lines). Green triangles are average concentrations from Pasche et al. 2011 (Pasche et al., 2011) from three different campaigns conducted in May 2006 and 2007 at different locations (Kibuye, Ishungu and Gisenyi). Green crosses are data from Gisenyi 2007. Blue rhombus correspond to measurements from Schmid et al. 2005 in the northern basin using a commercial Capsum Met sensor (Schmid et al., 2005). In the insert a zoom on the shallow data is presented with a log scale on the concentrations allowing a better comparison of the different datasets.
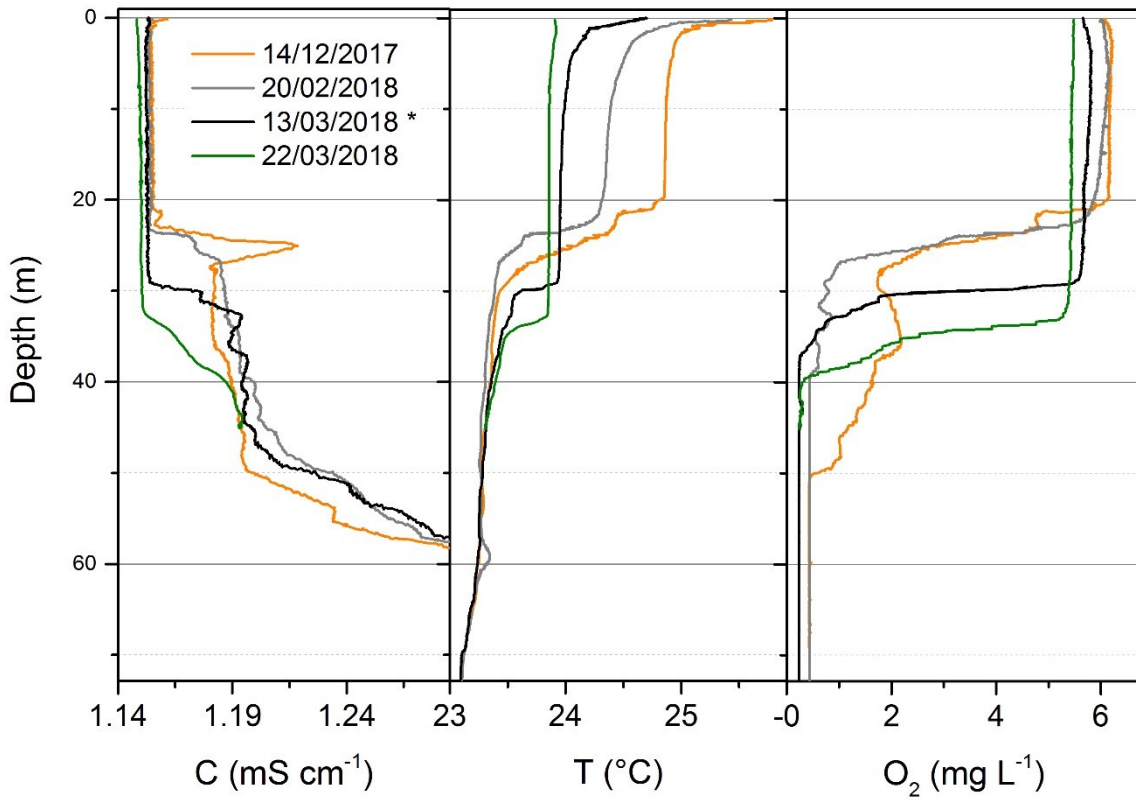
Figure 7. CTD (conductivity at 25°C, temperature and dissolved oxygen) data obtained a few months prior to the campaign. The black lines correspond to the conditions during the field measurements (*). The O_2 profiles highlight how the mixing layer extended down to 50 m depth during the previous dry season. From mid-December, the lake started to stratify at 25 m, while at the beginning of March the oxic layer increased down to 35 m depth.

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