



Glider Observations of Thermohaline Staircases in the Tropical North Atlantic Using an Automated Classifier

Callum Rollo¹, Karen J. Heywood¹, and Rob A. Hall¹

¹Centre for Ocean and Atmospheric Sciences, School of Environmental Sciences, University of East Anglia, Norwich, United Kingdom

Correspondence: Callum Rollo (c.rollo@uea.ac.uk)

Abstract.

Thermohaline staircases are stepped structures of alternating thick mixed layers and thin high gradient interfaces. These structures can be up to several tens of metres thick and are associated with double-diffusive mixing. Thermohaline staircases occur across broad swathes of the Arctic and tropical/subtropical oceans and can increase rates of diapycnal mixing by up to 5 five times the background rate, driving substantial nutrient fluxes to the upper ocean. In this study, we present an improved classification algorithm to detect thermohaline staircases in ocean glider profiles. We use a dataset of 1162 glider profiles from the tropical North Atlantic collected in early 2020 at the edge of a known thermohaline staircase region. The algorithm identifies thermohaline staircases in 97.7 % of profiles that extend deeper than 300 m. We validate our algorithm against previous results obtained from algorithmic classification of Argo float profiles. Using fine resolution temperature data from a fast-response 10 thermistor on one of the gliders, we explore the effect of varying vertical bin sizes on detected thermohaline staircases. Our algorithm builds on previous work with improved flexibility and the ability to classify staircases from profiles with poor salinity data. Using our results, we propose that the incidence of thermohaline staircases is limited by strong background vertical gradients in conservative temperature and absolute salinity.

1 Introduction

15 Thermohaline staircases consist of subsurface layers of near homogeneous salinity and temperature (referred to here as mixed layers), separated by thin layers with large temperature and salinity gradients (gradient layers). Staircases formation and growth are driven by double-diffusive processes that arise from the difference in molecular diffusivities of heat and salt. Heat diffuses 100 times faster than salt (Stern, 1960). Thermohaline staircases form where the vertical gradients of temperature and salinity have the same sign. These conditions most commonly occur in the Arctic, where cool fresh waters overlie warm salty waters, 20 and tropical/subtropical regions where warm salty surface waters overlie cool, fresh waters.

The effects of thermal expansion and haline contraction on seawater are critical to the formation of thermohaline staircases. The effects of these are often represented by two derived properties, the density ratio $R_\rho = \alpha\theta_z / \beta S_z$ and the Turner angle $Tu = \tan^{-1}(\alpha\theta_z - \beta S_z, \alpha\theta_z + \beta S_z)$, where α is the thermal expansion coefficient, β is the haline contraction coefficient, θ_z and S_z are the vertical gradients in conservative temperature and absolute salinity (Ruddick, 1983). The density ratio can be



25 calculated from the Turner angle with $R_\rho = -\tan(Tu + 45^\circ)$ (You, 2002). The Turner angle categorises the water column into sections that are statically unstable, prone to salt fingers, prone to diffusion-convection or doubly stable (Ruddick, 1983).

In this study of the tropical North Atlantic, warm salty Subtropical Underwater (22 - 25 °C, 37.0 - 37.6 g kg⁻¹) overlies cooler fresher Antarctic Intermediate Water (4-6 °C, 34.7-35.0 g kg⁻¹) (Fer et al., 2010). In this case, the mechanism driving mixing in the gradient layers is salt finger instability (Radko, 2005). This instability can spontaneously transform smooth, statically stable profiles into stepped patterns such as those in Fig. 1. This instability can occur where $45^\circ \leq Tu \leq 90^\circ$ (Fig. 1.c). Laboratory and theoretical studies have concluded that diapycnal mixing rates of heat and salt are elevated in thermohaline staircases (Schmitt, 1981 & Radko and Smith, 2011). Previous work by Schmitt et al. (2005) estimated that thermohaline staircases raise diapycnal mixing rates in the tropical North Atlantic by a factor of five. Mixing rates control critical oceanographic processes including nutrient fluxes (Oschlies et al., 2003) and the meridional overturning circulation (Kuhlbrodt et al., 2007).
35 Due to their effect on mixing, the global incidence of thermohaline staircases, and the mechanisms that govern them, are the subject of ongoing research. This study aims to improve detection and quantification of thermohaline staircases using ocean gliders.

The tropical North Atlantic has been known to host thermohaline staircases since the 1970s (Schmitt et al. (1987), and references therein). Using ship CTD casts and expendable bathythermographs (XBTs) from ships and aircraft, thermohaline staircases were identified over an area exceeding one million square kilometres by the C-SALT experiment (Schmitt et al., 1987). Staircases were observed at depths of 420-650 m, with individual steps 5-30 m thick. Subsequent studies using a fast-response thermistor chain (Marmorino et al., 1987), tracer release and fine-structure high resolution profilers (Schmitt et al., 2005), seismic oceanography (Fer et al., 2010) and Argo floats (van der Boog et al., 2021), henceforth VDB, have observed staircases with similar bulk statistics in this region. See Table 5 of VDB for more details. The area identified as strong or weak
45 staircase by Schmitt et al. (1987) appears to be consistent in time, with subsequent studies by Marmorino et al. (1987) and Fer et al. (2010) observing breakdowns of steps at the edges of these zones.

While the exact formation mechanisms of thermohaline staircases are still a topic of discussion (Radko, 2020), VDB, several key conditions have been identified. Firstly, the Turner angle must fall in the regime favourable to double diffusive processes of diffusion-convection ($-90^\circ \leq Tu \leq -45^\circ$) or salt finger ($45^\circ \leq Tu \leq 90^\circ$). Secondly, the density ratio must be within a critical range. The lower bound for R_ρ is 1, where the gradients in salinity and temperature balance and there is no density stratification. Bryden et al. (2014), Schmitt et al. (1987) and Fer et al. (2010) all observed well ordered staircases up to $R_\rho = 1.7$, with irregular “steppy” profiles up to R_ρ of 2.0 or greater. Theoretical work by Radko (2005) suggests that staircases can only form at $R_\rho < 2$. Fer et al. (2010) consider the range $1 < R_\rho < 2.5$ as conducive to forming thermohaline staircases in the tropical North Atlantic. Energetic features such as velocity shear, slope currents and internal waves can prevent the
55 formation of staircases (Fer et al., 2010; Buffett et al., 2017); though in some cases, the staircases are strong enough to resist breakup (Schmitt et al., 1987), and can even dampen internal wave activity (Radko, 2020). In this paper we suggest that strong vertical gradients in salinity and temperature also constrain the formation of thermohaline staircases.

To explore the incidence and structure of thermohaline staircases in the tropical North Atlantic, we analysed over 1000 profiles collected by three ocean gliders in early 2020. Gliders have previously been used to observe thermohaline staircases

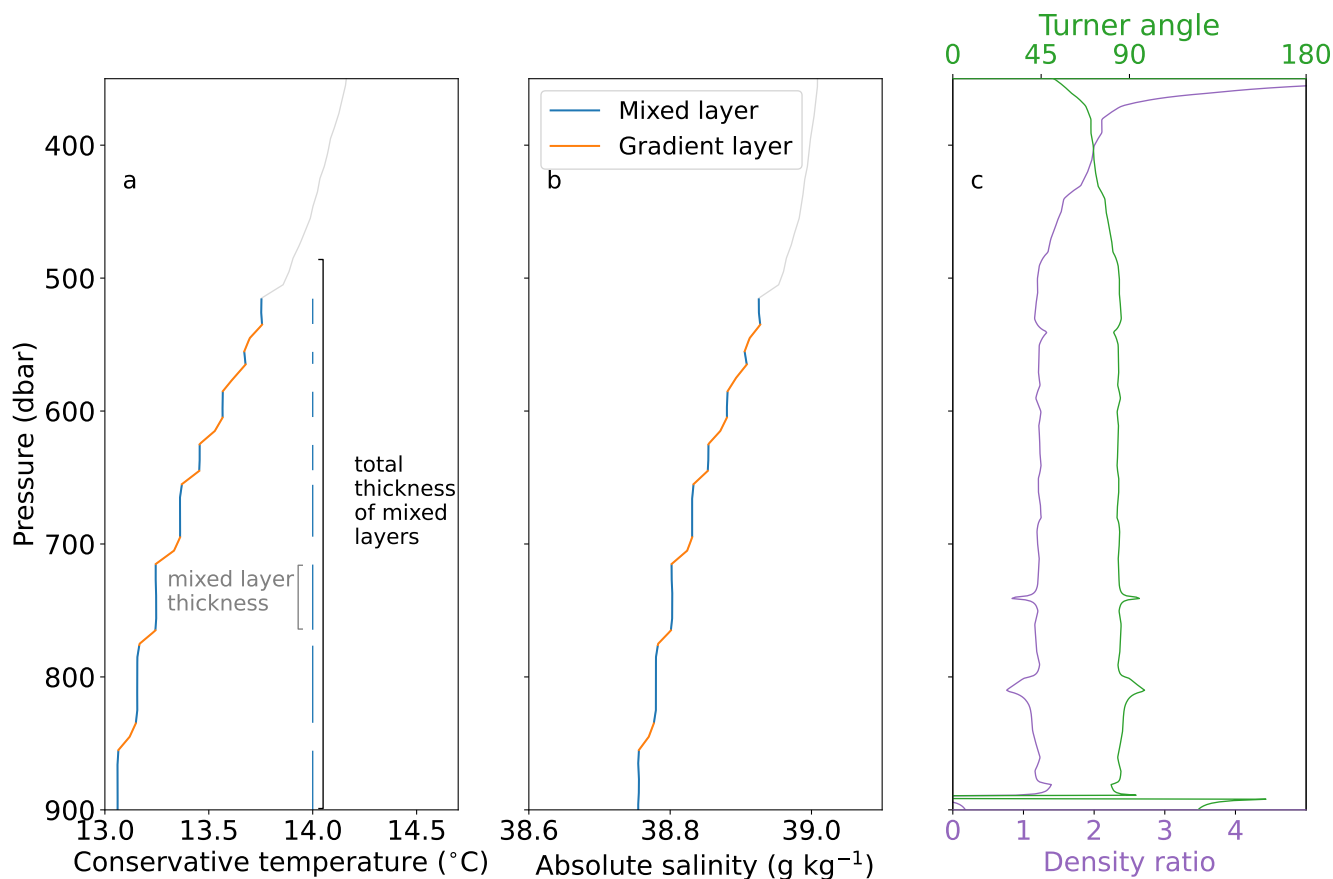


Figure 1. Example thermohaline staircase from Argo float 6901769 at 8.9° E, 37.9° N. Grey line is 1 dbar averaged temperature (a) and salinity (b), with blue and orange lines marking the identified steps of the staircase. (c) Corresponding profiles of Turner angle and density ratio.

60 in the Tyrrhenian Sea in the Mediterranean, primarily to relate seismic reflectors to thermohaline structures (Buffett et al.,
2017). However this study is, to our knowledge, the first of its kind in the tropical North Atlantic. This is also the first study
to identify thermohaline staircases in glider profiles algorithmically. Data collection is detailed in Sect. 2. The thermohaline
classifier is described in Sect. 2.2. Results are presented in Sect. 3 and discussed in Sect. 4, with subsections on scale sensitivity
and classifier limitations in Sect. 4.2 and Sect. 4.3. We summarise our conclusions and recommendations for future avenues of
65 study in Sect. 5.

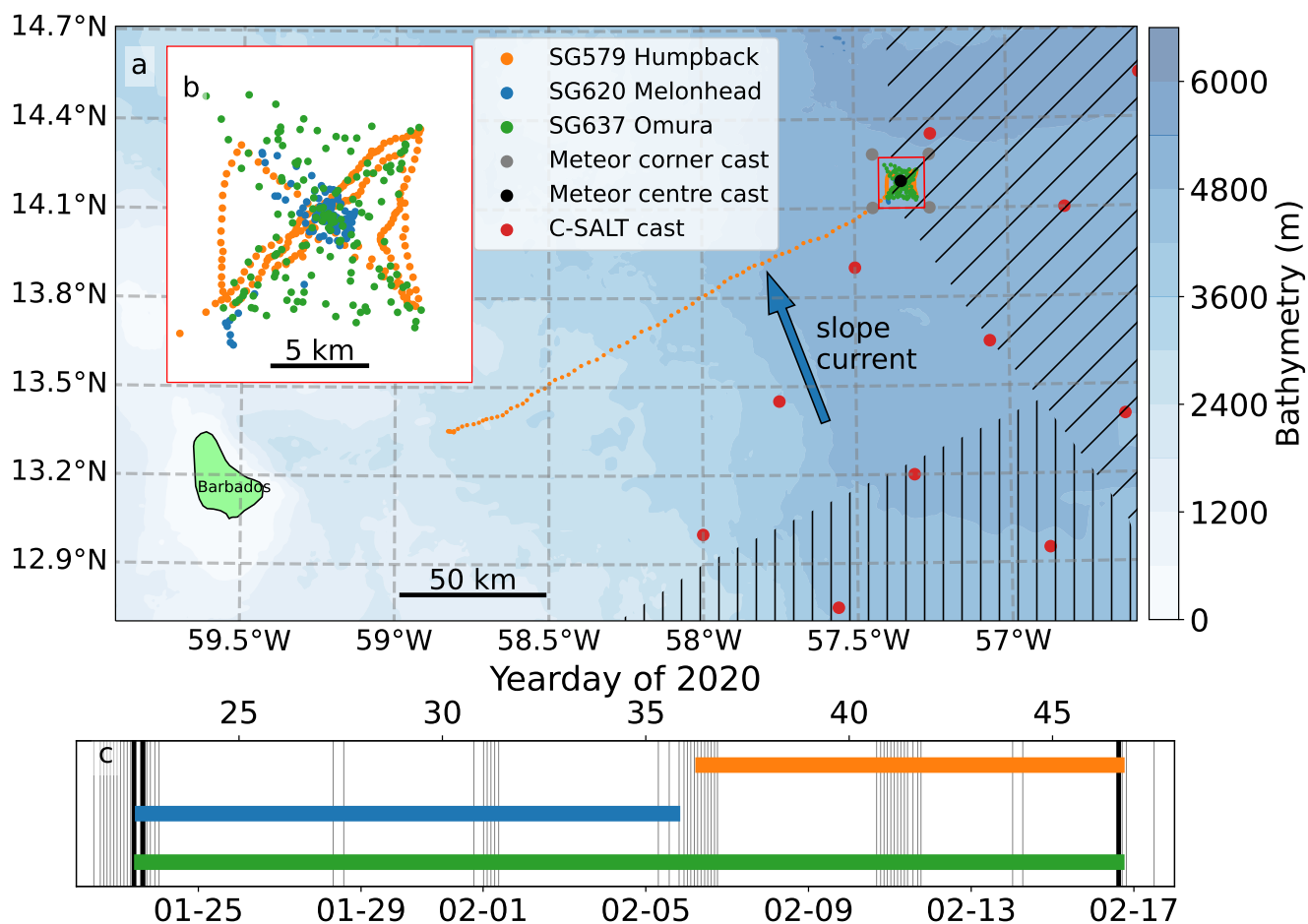


Figure 2. (a) Glider survey map. Red dots are CTD casts conducted during the C-SALT experiment in Spring 1985 (Schmitt, 1987). Diagonal and vertical hatching respectively delineate the approximate areas of strong and weak staircases identified by Schmitt et al. (1987). (b) Zoomed detail of bowtie outlined in red on (a). (c) Temporal overlap of glider observations at the bowtie and nearby *Meteor* CTD casts. *Meteor* corner casts were taken at grey dots on map. *Meteor* centre casts were taken at the black dot. Colours match legend in (a).

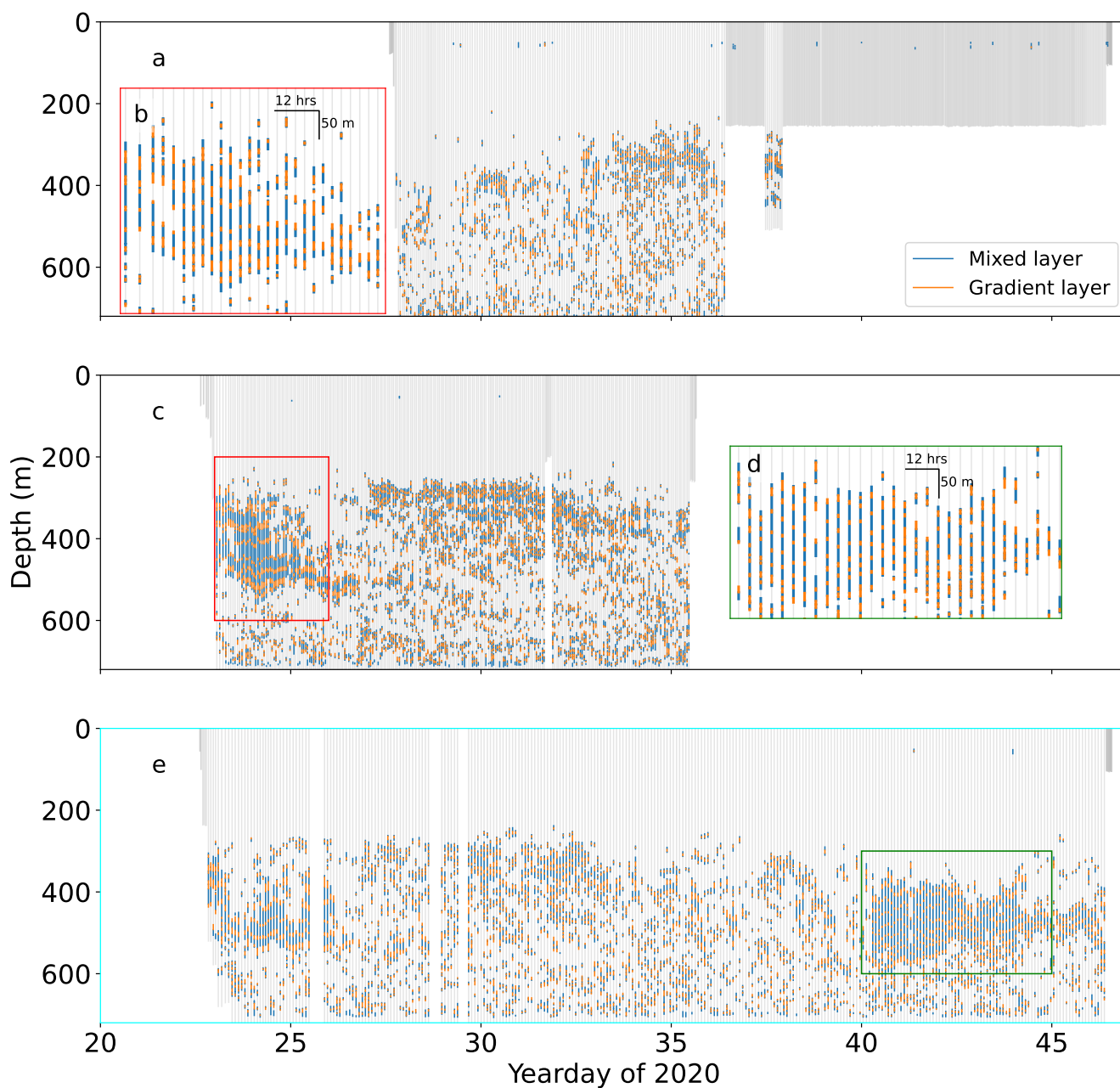


Figure 3. All thermohaline staircases detected in glider profiles. (a, c & e) data from gliders SG579, SG620, and SG637 respectively. (b & d) show expanded sections from boxes in c & e in the corresponding colour. Data from (e) are the basis for remaining figures in this manuscript, except where otherwise stated.



2 Data collection and processing

2.1 Glider data

During January and February 2020, the RV *Meteor* surveyed the tropical North Atlantic, 200 km ENE of Barbados (Fig. 2), as part of the EUREC⁴A campaign (Stevens et al., 2021). During this cruise, the UEA glider group deployed three Seagliders. Seagliders are small buoyancy powered autonomous vehicles with wings that dive with a sawtoothed profile (Eriksen et al., 2001). Seagliders dive to a maximum of 1000 m with a vertical speed of around 0.1 m s^{-1} . In contrast to Argo floats, gliders are capable of manoeuvring to maintain position or follow a survey pattern. Here, each glider dive limb is treated as a separate profile, so that a single descent-ascent cycle yields two profiles. The temporal overlap and dive depths of the three gliders are shown in Fig. 3. All glider dives were completed within the 10 km wide bowtie pattern shown in Fig. 2 except SG579, which was deployed 150 km SW of the bowtie and arrived on yearday 36. Gliders SG579, SG620 and SG637 completed 295, 131 and 155 dive cycles respectively, yielding a total of 1162 profiles for analysis. The gliders sampled every 5 seconds, for a vertical resolution of approximately 0.5 m. Owing to a shallow dive slope, SG637 stalled during dives 22, 23, 41, 42, 43, and 47. Glider stalling reduces water flow through the unpumped CT sail, affecting temperature and conductivity measurements. We removed these dives from the dataset, as can be seen in the gaps in Fig. 3.

Glider profiles were processed using the UEA Seaglider Toolbox (Queste, 2014). This included tuning the hydrodynamic flight model following Frajka-Williams et al. (2011) and thermal lag corrections following Garau et al. (2011). After processing the glider profiles, temperature and salinity profiles were compared with CTD casts conducted by the *Meteor* (black vertical lines in 2.c). Quality controlled CTD profiles were provided by D. Baronowski (Baronowski, 2020). At the bowtie, SG637 dived to 750 m for 25 days, completing a dive approximately every 4 hours. SG579 only dived to 250 m and SG620 was recovered after 13 days. As SG637 recorded the most comprehensive set of observations, it is used for the majority of the subsequent analysis.

To apply the thermohaline staircases classifier to the dataset, we require data at regular depth intervals to ensure that features are consistently identified throughout the dataset. To achieve this, each profile was binned into 1 m depth bins using the median value of samples within the bin. Derived variables including the Turner angle, density ratio and vertical gradients in salinity and temperature were calculated at 1 m intervals using a 50 m vertical bin to ensure smooth profiles, following the methods of VDB. A 50 m averaging interval is used as a smaller depth interval can be influenced by individual staircase steps (Shibley et al., 2017). Throughout this paper, temperature refers to conservative temperature, salinity refers to absolute salinity and density refers to potential density. All were calculated using the gsw toolbox implementation of TEOS-10 (McDougall et al., 2010; McDougall et al., 2011). Yeardays are used throughout the paper. Yeardays start at 0 on the first of January 2020. Figure 2.c uses both yeardays and calendar dates for comparison.

2.2 Thermohaline staircase classifier

To evaluate thermohaline staircases in glider profiles, we wrote a classifier following VDB. VDB's detection algorithm, identifies thermohaline staircases in a CTD profile using five steps:

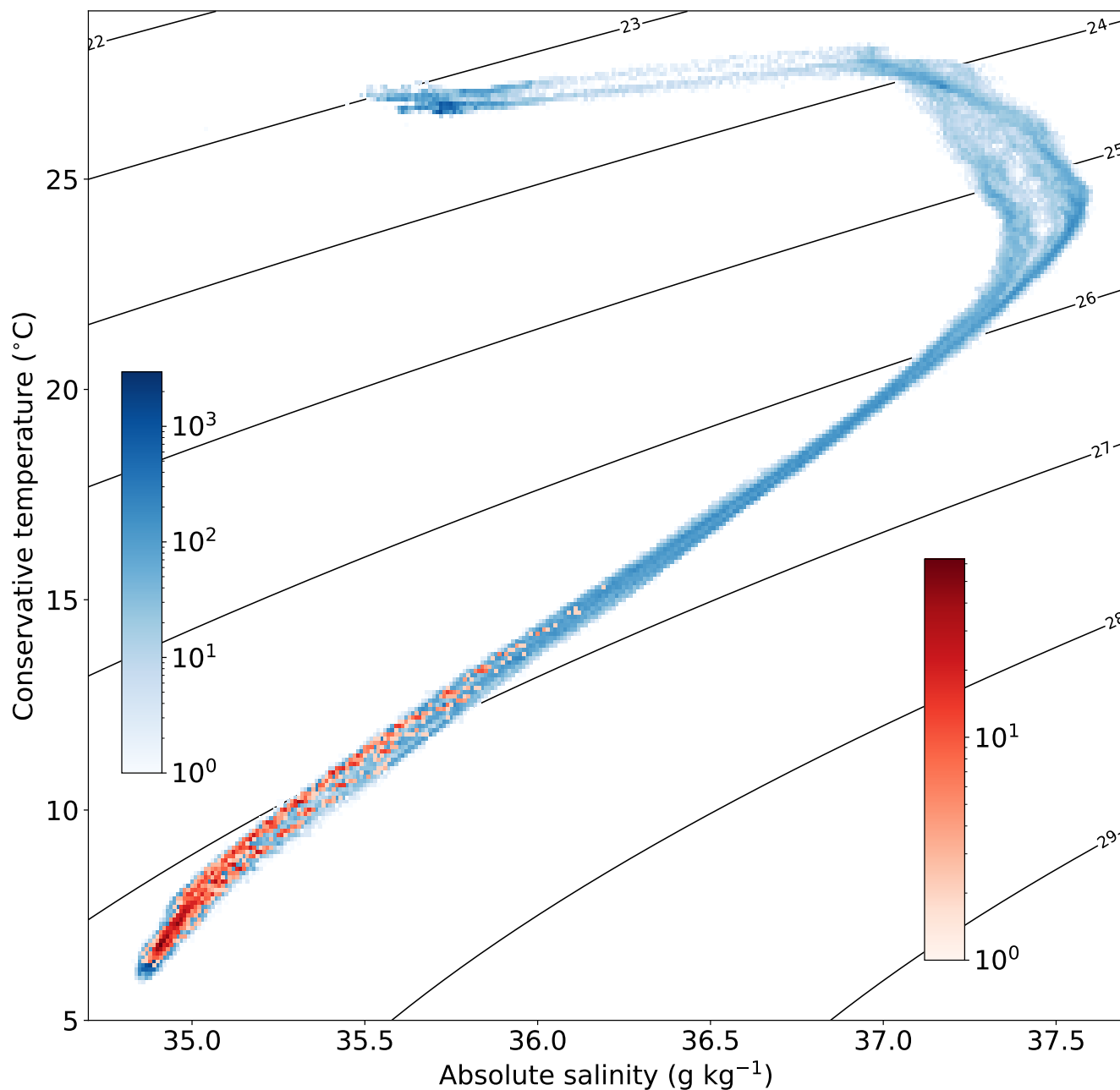


Figure 4. Observation density of SG637 temperate and salinity measurements (blue) and identified mixed layers (red). Spacing of the grid is 0.01 g kg⁻³ in absolute salinity and 0.1 °C in conservative temperature. Colour scales are the number of observations in each grid cell. Black lines are isopycnals.

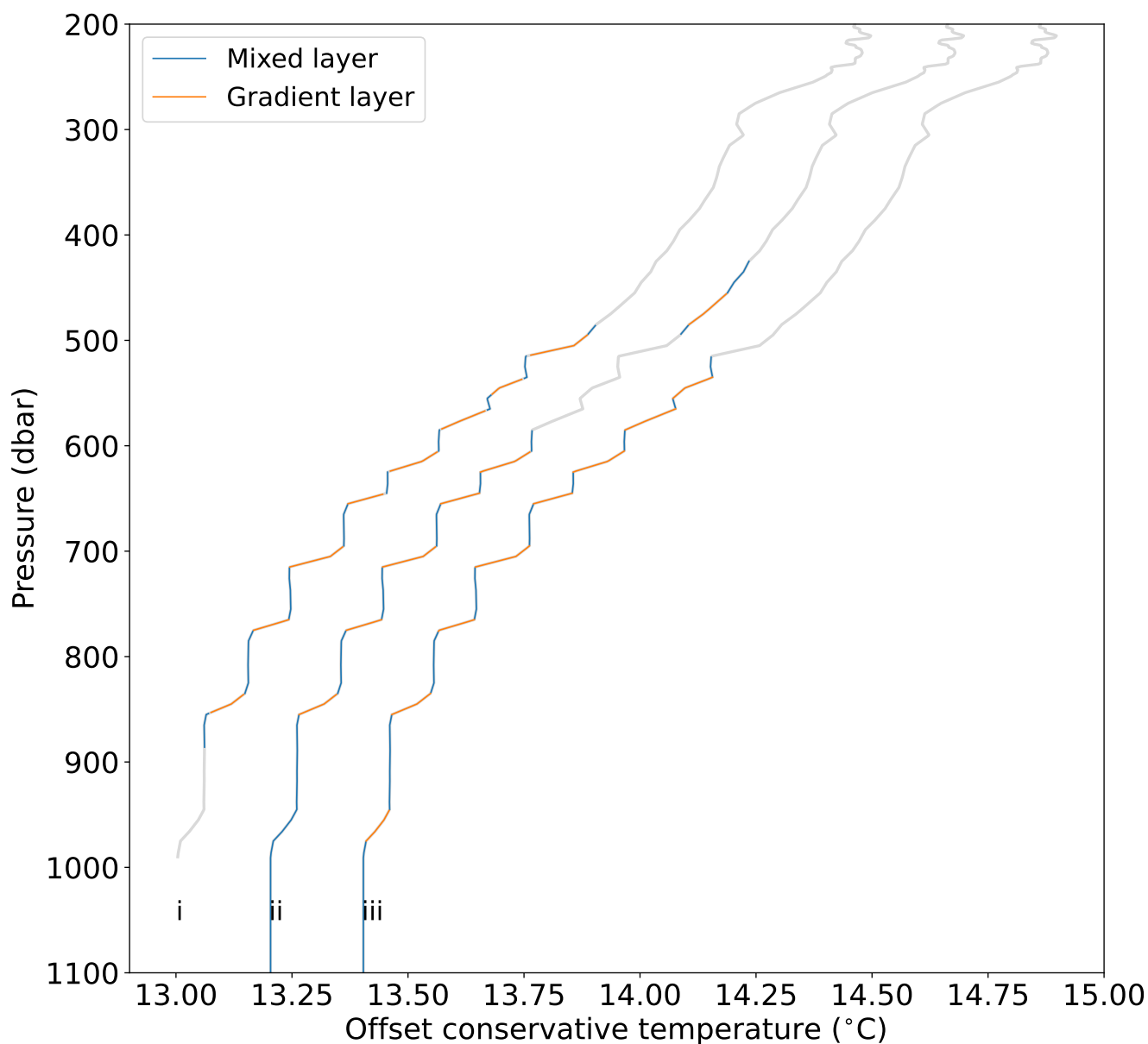


Figure 5. The same Argo profile shown in Fig. 1 classified three times. Three lines on this plot are (i) VDB's result, (ii) our classifier on default settings, and (iii) our classifier with a 10 % decrease in step height ratio and 4 % decrease in maximum permitted density gradient. The first profile is at the correct temperature, subsequent profiles are offset by 0.2 °C



- 100 1. Parts of the profile with vertical temperature, salinity and density gradients below a threshold value are classed as mixed layers.
 2. Sections between mixed layers are preliminarily classed as gradient layers
 3. Gradient layers are excluded if they exceed a maximum thickness, are thicker than the neighbouring mixed layers, or exhibit less variability in salinity and temperature than neighbouring mixed layers. This ensures that mixed layers are separated by thin, steep interfaces.
 - 105 4. Gradient layers are classified into a double diffusive regime: salt-finger if the overlying mixed layer is warmer and saltier than the underlying mixed layer, diffusive-convective if the overlying mixed layer is cooler and fresher than the underlying mixed layer.
 5. Staircases are identified as uninterrupted series of steps in the same diffusive-convective regime. This step removes thermohaline intrusions.
- 110 VDB's algorithm was designed to classify a global database of Argo profiles. It performs this duty well, but was specifically written to ingest Argo profiles at 1 dbar vertical resolution. Due to hard coded aspects of VDB's algorithm, it was not possible to apply it directly to our glider dataset. To identify staircases in our dataset, we built our own classifier (Rollo, 2021a) following the steps outlined in VDB, with the following adaptations:
- Able to process profiles at any regularly spaced step in pressure or depth.
 - 115 – Optional user-defined maximum mixed layer height.
 - Optional plotting to show which layers are identified and discarded at each of the steps outlined by VDB in Sect. 3.
 - Option to classify step shape using only vertical variation in temperature, rather than temperature, salinity and density. This is useful if salinity data are poor or recorded as a lower frequency than temperature, as is the case when using a fast-response thermistor.
 - 120 – Each processing step as a separate, documented function.
 - Software tests and validation against synthetic and field data.
 - Software published in version-controlled repository (GitHub) to retain full development history.

These adaptations were driven by a need for greater flexibility in the classifier, and requirements imposed by the glider profiles. Substantial salinity spikes were present in the salinity profiles from all three gliders (Fig. 7.b orange line). To remove
125 these spikes, a 5 m mean boxcar moving average filter was applied to the salinity profiles fed to the classifier (Fig. 7.b, green line). This removed the spikes, but smoothed the edges of the steps that the classifier identifies. To resolve this problem, we made the classifier able to identify the shape of steps using only temperature profiles. In this mode, salinity profiles are used

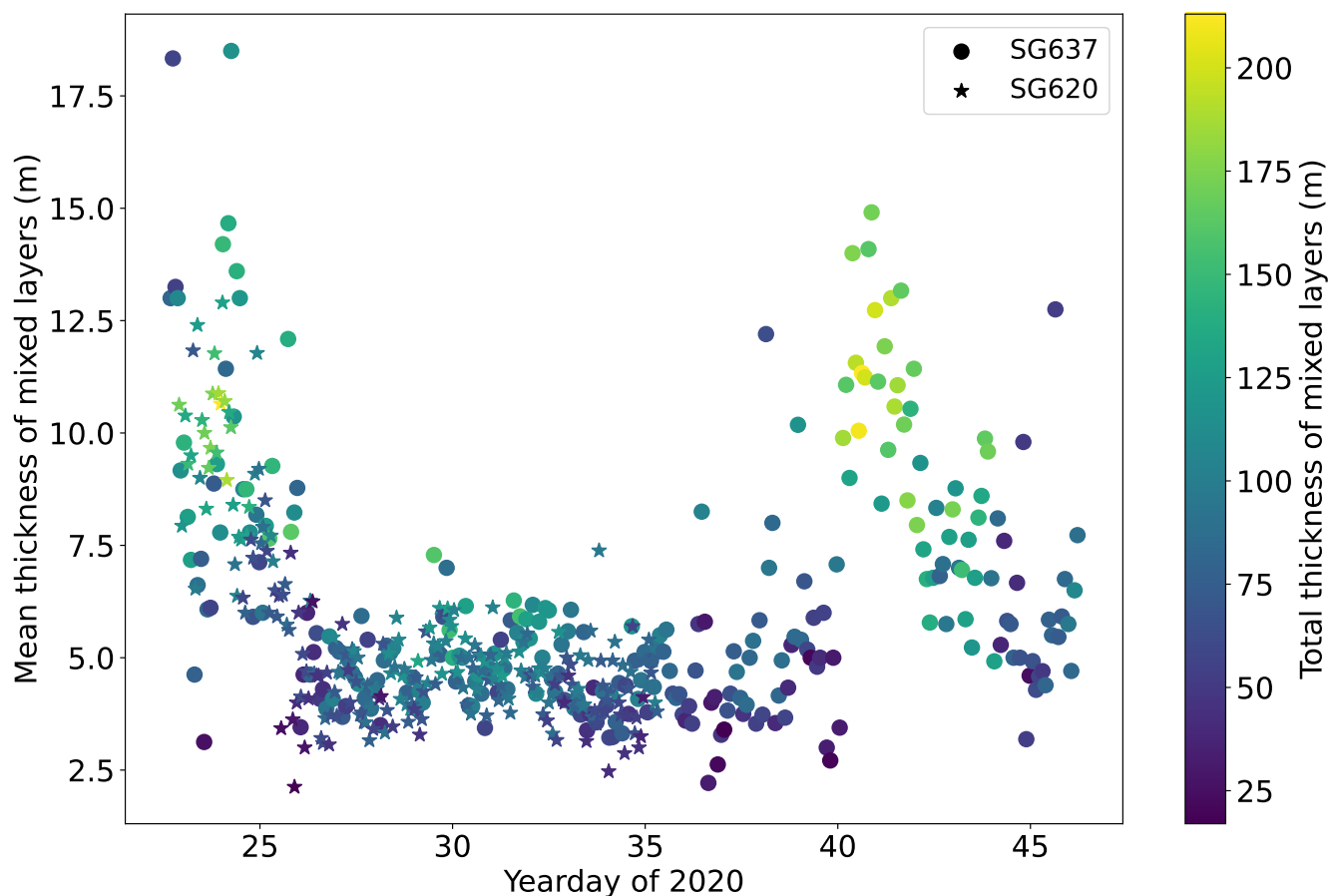


Figure 6. Mean thermohaline staircase mixed layer thickness observed by SG620 and SG637.

to classify the staircase into the salt finger regime or the diffusive-convective regime. The classifier includes software tests to ensure that this use of temperature only for initial classification does not change the identification of staircases.

130 There were no Argo floats in the vicinity when our gliders were deployed, so we could not compare the output of our algorithm and VDB's algorithm on profiles from the EUREC⁴A campaign. Instead, we applied our classifier to the Argo profile used as a demonstration of VDB's algorithm by VDB Fig. A2. The results of this comparison are shown in Fig. 5.

Our classifier identified 14205 thermohaline steps in the glider profiles. The glider dataset comprised 1162 vertical profiles recorded over 56 glider days. To make quantitative comparisons across the dataset, we use bulk statistics to analyse how the
135 staircases changed over time. We define total thickness of mixed layers to be the total vertical extent of the profile identified as a part of a mixed layer in the thermohaline staircase, as shown in Fig. 1.a. Mean mixed layer thickness is similarly calculated on a per-profile basis. Calculating these bulk values enables us to evaluate the temporal evolution of thermohaline staircases, and visualise datasets too large to plot directly.

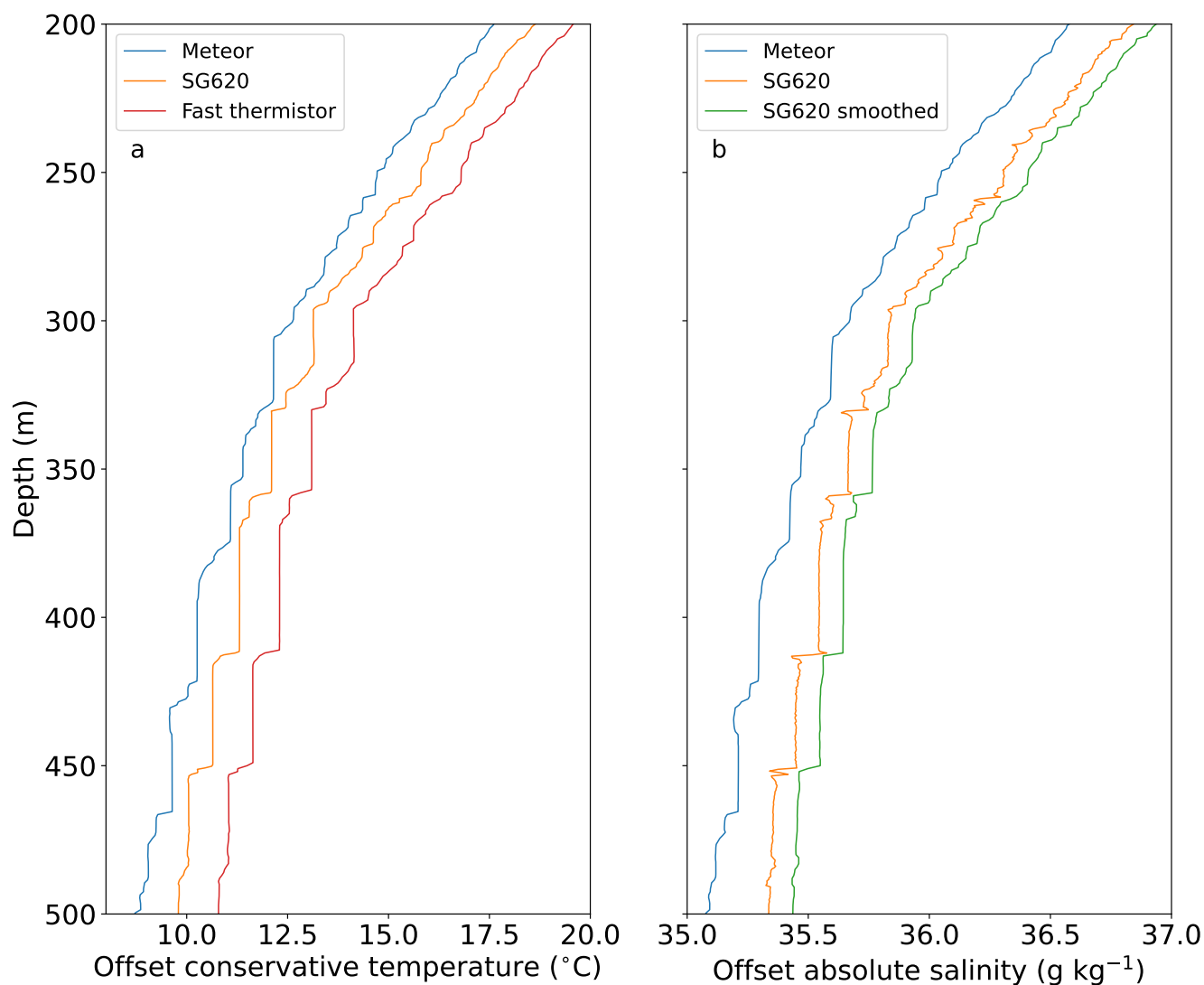


Figure 7. (a) Temperature profiles from *Meteor* CTD, SG620 CT sail and fast-response thermistor. (b) Salinity from *Meteor*, salinity from SG620 and SG620 salinity smoothed with a 5 m mean window. The profile from the *Meteor* was taken at the same location 24 hours before the glider dive. As in Fig. 5 the first profiles is correct, subsequent vertical profiles are offset by 1 °C or 0.1 g kg⁻³



3 Results

140 Thermohaline steps were identified in 97.7 % of profiles that extended below 300 m. In profiles with at least one mixed layer, the mean number of mixed layers per profile was 14.3. However, coherent series of large steps were more restricted, both temporally and spatially. Staircases with more than three steps greater than 20 m were only observed at the bowtie, and only on two occasions: Yearday 23-25 (Fig. 3.b) and yearday 40-44 (Fig. 3.d). The changing thickness of steps is represented in Fig. 6 which shows the two events of strong staircasing as peaks in mean mixed layer thickness and total mixed layer thickness.

145 The small differences between values recorded by SG637 and SG620 can be attributed to the distance between the two gliders, typically ≈ 5 km (Fig. 2).

Internal wave activity displaced the interfaces vertically, particularly in the lower pycnocline around 300 m (Fig. 8). These vertical displacements were strongest at the semi-diurnal frequency, and had a maximum amplitude of around 5 m. SG579 observed few steps at its deployment location. As SG579 travelled eastward larger staircases were encountered and the mini-
150 mum observed depth of staircases decreased. A front was observed by SG579 as the glider passed over the continental slope on yearday 34. Decreases of 0.5 °C and 0.2 g kg⁻³ in the uppermost 3 m coincided with a peak in chlorophyll a fluorescence and a broad along-slope current of 15 cm s⁻¹. Once past the front and over the abyssal plain, SG579 observed larger and more coherent staircases similar to SG620 and SG637 (Fig. 3.a). Total mixed layer thickness increased from 58 ± 25 m to 90 ± 26 m after yearday 34.

155 SG637 observed a sloping front later in the mission. First observed at 200 m on yearday 35, the front reached 750 m, the maximum dive depth of the glider, on yearday 40 (Fig. 8 a&c). The passage of this front was followed by the second period of large, coherent staircases at 400-600 m, with total mixed layer thickness increasing from 60 ± 23 m to 146 ± 38 m in the three days following yearday 40.

Using the observations of all three gliders, we calculated bulk statistics following VDB. Ranges quoted are the 2.5 and 97.5
160 percentiles. Depth 277-858 m, temperature steps 0.01-0.69 °C, salinity steps 0.001-0.12 g kg⁻³, gradient layer thickness 1-12 m, mixed layer thickness 1-21 m. The smallest features resolvable within our dataset are 1 m thick. 73 % of the steps identified were in the salt-finger regime. Mixed layer thickness varied with R_ρ (Fig. 11), the largest staircases were observed around $R_\rho = 1.7$, with a thick tail of steps at larger values of R_ρ . No steps were observed at $R_\rho < 1$ (Fig. 11).

Staircases in the salt finger regime require a Turner angle between 45 and 90 degrees (red area of Fig. 9a) and a density
165 ratio between 1 and 2.5 (Fig. 9b). These constraints alone do not explain the distribution of thermohaline staircases in the glider profiles we collected. The absolute vertical gradients of temperature and salinity (Fig. 9.c & d) partially account for this discrepancy. The vertical gradients are calculated over 50 m to prevent individual thermohaline steps from affecting the results, in the same manner as the Turner angle is calculated (Shibley et al., 2017). Using the critical values of Turner angle and density ratio, as well as upper limits of temperature and salinity gradient, we construct masks of where we expect thermohaline
170 staircases to form. These masks are shown in Fig. 10, with a combined mask of the area that matches all criteria in Fig. 10 d. These masks suggest that staircases with steps larger than 1 m do not form where the absolute vertical gradients in temperature or salinity exceed 0.05 °C m⁻¹ or 0.005 kg m⁻¹ respectively.

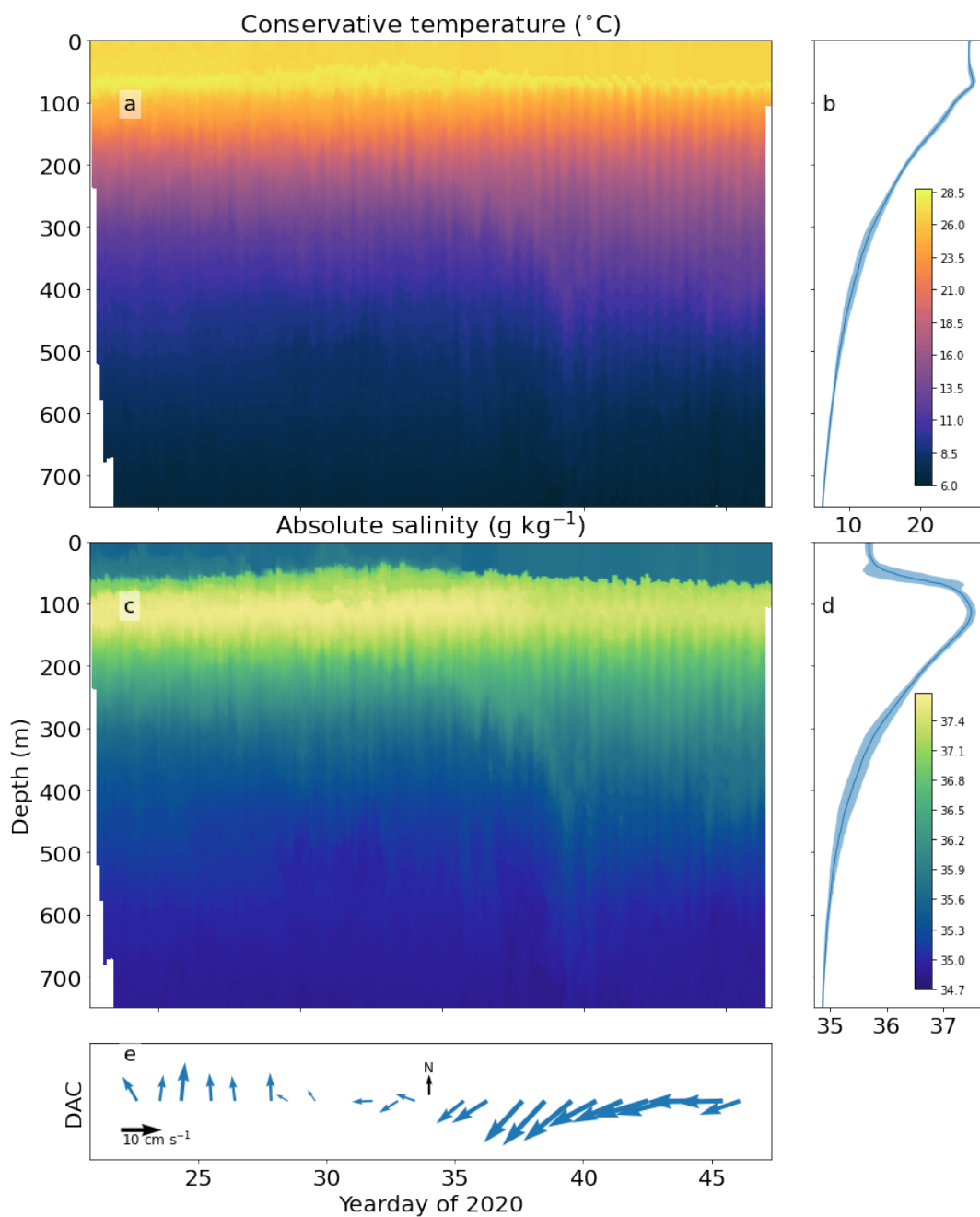


Figure 8. (a) Gridded mean conservative temperature from SG637. (b) Mean conservative temperature profile with uncertainty of 1 standard deviation shaded. (c & d) as (a & b) for absolute salinity. (a & c) gridding is 1 m vertically performed on a per-profile basis. (e) Daily mean of the dive average current (DAC).

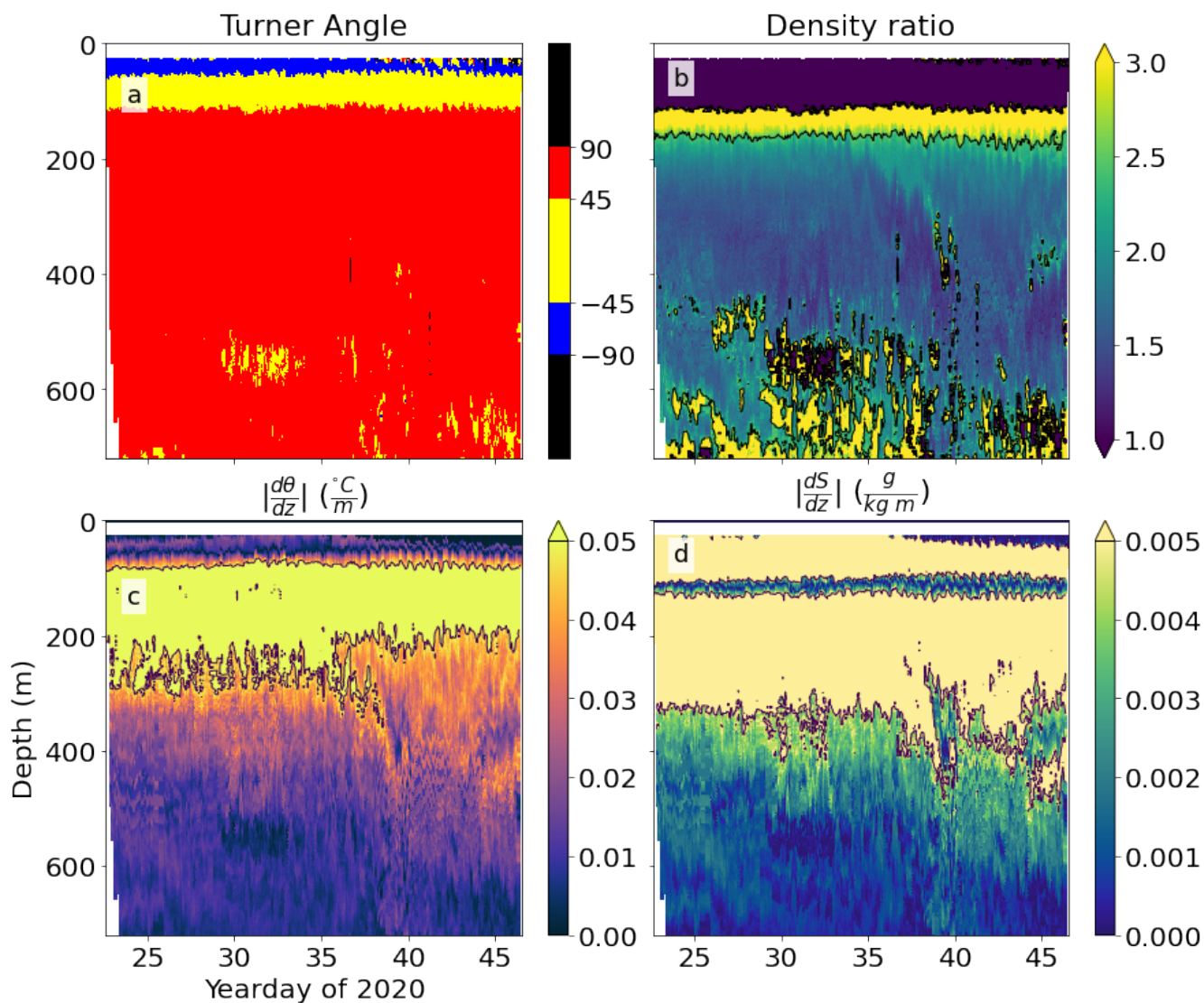


Figure 9. Key variables for the formation of thermohaline staircases, calculated from SG637 profiles. a) Turner angle b) density ratio c) absolute vertical temperature gradient d) absolute vertical salinity gradient.

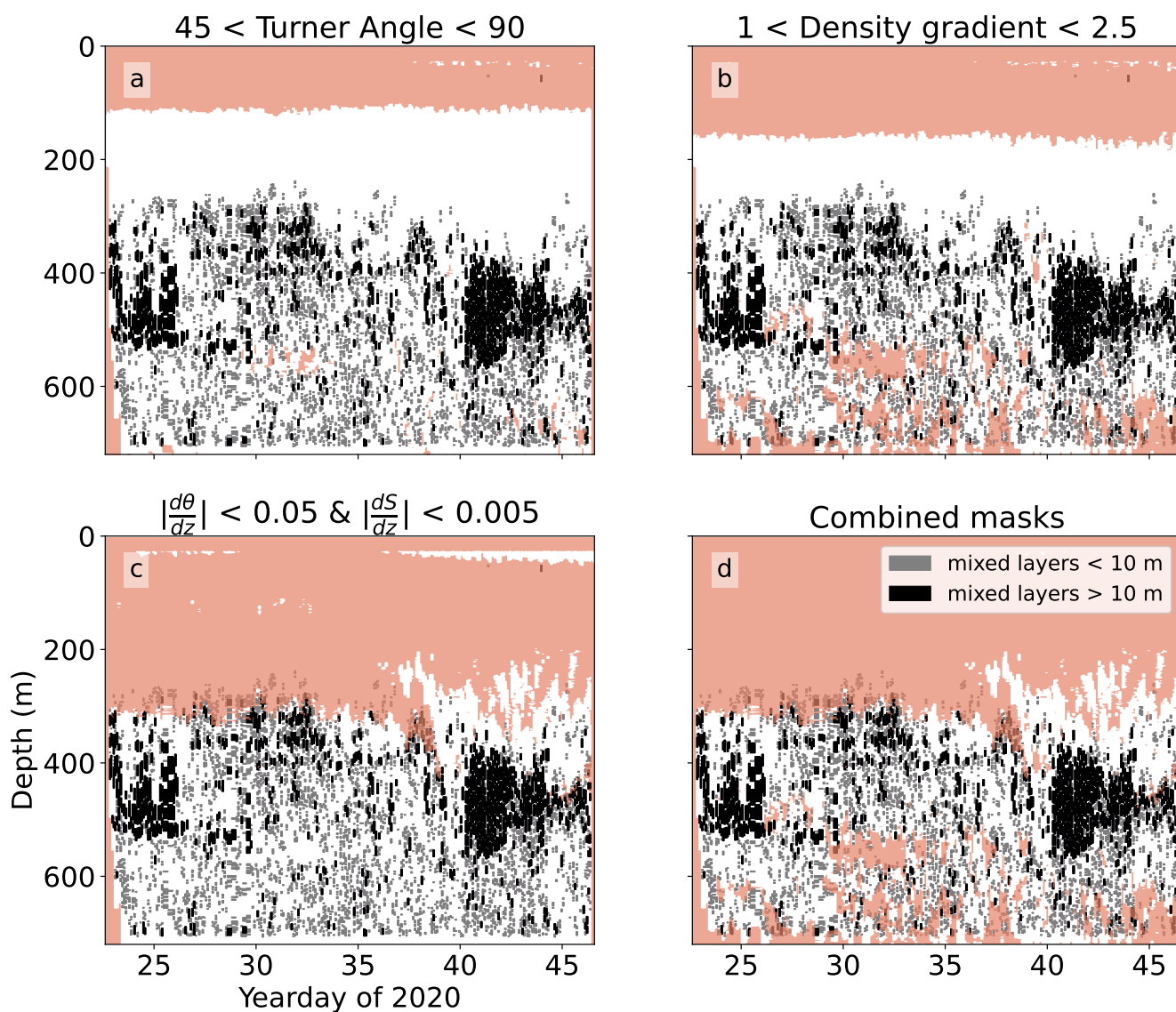


Figure 10. Masks shading the conditions in Fig. 9. Red areas mask where the conditions are not met. Grey blocks are the location of thermohaline mixed layers, black blocks are mixed layers thicker than 10 m.

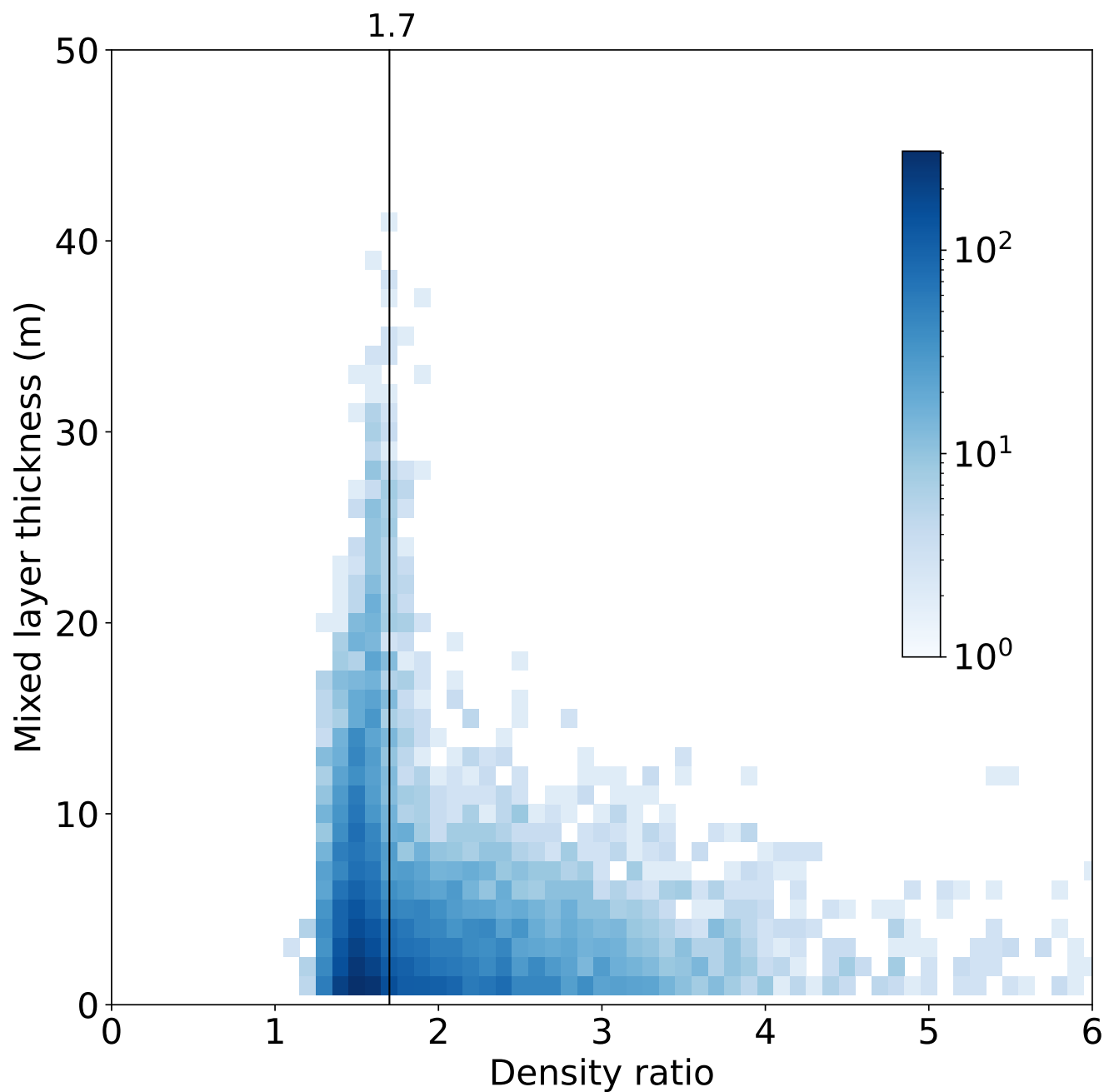


Figure 11. Observations of mixed layers classified from all three gliders between 100 and 800 m depth. Colourbar shows number of observations in each grid cell. Cell spacing of 0.1 in density ratio, 1 m in mixed layer thickness. Vertical black line marks the density ratio of 1.7.



4 Discussion

4.1 Thermohaline staircases

175 The structures we observed during periods of strong staircasing are very similar to those encountered during the C-SALT
campaign. Schmitt et al. (1987) recorded mixed layers of 5-30 m thickness separated by gradients with temperature and salinity
jumps of 0.5-0.8 C and 0.1-0.2 psu in the area identified as strong staircasing. The glider bowtie is at the edge of this region
(Fig. 2). This may explain why we did not observe coherent staircases throughout our observational period. Fer et al. (2010)
also conducted their observations at the edge of the strong staircasing zone identified by C-SALT and observed intermittent
180 staircases. The location of our observations at the edge of the staircase zone would also explain the slightly smaller step sizes
and temperature and salinity changes observed compared to the averages reported by Schmitt et al. (1987). The rapid apparent
breakdown of staircases confirms observation by Marmorino et al. (1987) of thermohaline layers disappearing within a few
km. Due to the sampling pattern of the gliders, we cannot definitively determine whether this rapid transition from staircase to
non-staircase is a breakdown in the structure or the advection of the edge of the staircase zone past the glider bowtie. Given the
185 historic extent of the staircases in this region (Fig. 2) and their known persistence of at least 6 months (Schmitt et al., 1987),
the latter explanation is more likely.

Density ratio is generally assumed to be the main factor controlling thermohaline staircases formation and persistence.
In agreement with previous studies in this region and elsewhere, we observed the largest steps around $R_\rho = 1.7$ (Fig. 11).
However, we also observed mixed layers at substantially larger R_ρ , though the maximum thickness of these layers was smaller,
190 as predicted by Radko (2005). R_ρ alone cannot account for the incidence of staircases, we do not observe staircases shallower
than 250 m, despite the favourable density ratio (Fig.s 9b and 10b). Similarly, Schmitt et al. (1987) did not observe any staircase
structure at the R_ρ minimum around 200 m depth, concluding that $R_\rho < 1.7$ is a necessary but not sufficient condition for the
formation of staircases.

We propose that strong background vertical gradients in temperature and salinity prevent the formation of thermohaline
195 staircases. As shown in Fig. 9, the water column at 200-250 m has a Turner angle and density ratio conducive to staircasing,
but also has large gradients in temperature and salinity. Combining masks of all four key variables creates a better predictor
of where staircases of large steps will form, particularly those with steps greater than 10 m in thickness (Fig. 10). This lack
of steps in the upper pycnocline, also reported by Schmitt et al. (1987) & Fer et al. (2010) could also be due to observational
limitations. In a manner analogous to internal waves, large steps form where background gradients in temperature and salinity
200 are small (Fig. 5). This is most apparent in the Mediterranean, where the largest steps of several hundreds of metres are found
deep in the water column, where background gradients are very small (Buffett et al., 2017). Where background gradients are
strong, we would expect small thermohaline steps, possibly below the resolution of our 1 m binned profiles.

Predicting the presence of thermohaline staircases from background gradients can have practical benefits for sub-grid
parametrisation. Thermohaline staircases in the tropical North Atlantic can increase diapycnal mixing rates by a factor of 5
205 (Schmitt et al., 2005). Most ocean models lack sufficiently fine vertical resolution to directly represent thermohaline staircases
comprised of mixed layers ≈ 10 m and gradient layers ≈ 1 m in the open ocean environment where thermohaline staircases are



most often found. The enhanced diapycnal mixing driven by staircases could be parametrised where key conditions are met, removing the need for direct representation of staircases.

The acoustic impedance contrast across a thermohaline step is an ideal reflector for seismic oceanography. Previous studies (Fer et al., 2010; Buffett et al., 2017) have successfully exploited this characteristic to map out thermohaline staircases over large spatial scales. Often, these 3D maps of staircases are constructed from seismic data and XBTs. Gliders can ably complement the analysis of seismic data. Gliders are particularly valuable for their ability to maintain station or sample a specific region distant from the ship conducting the seismic survey, unlike free floating Argo floats or XBTs which are single use and must be deployed at the required site by ship or aircraft. Seagliders are a useful tool for observing thermohaline staircases in the tropical North Atlantic as the staircases are limited to the uppermost 800 m, well within Seagliders 1000 m maximum depth rating. As opposed to the Tyrrhenian Sea where staircases extend deeper than 1500 m (Buffett et al., 2017). This study has proven the usefulness of gliders in this region. Future seismic oceanography studies in the tropical North Atlantic could benefit from the inclusion of gliders in a similar manner to Buffett et al. (2017).

This is a small study, with less than two months of observations. More work should be done to test this hypothesis and the critical values of temperature and salinity gradients. It would be beneficial to test if observations in other staircasing regions such as the Arctic and Mediterranean exhibit similar behaviour. In particular, staircases in Arctic regions dominated by diffusive-convective processes typically have smaller steps than those in the salt finger regime (VDB). A high resolution glider dataset from the Arctic could reveal more small scale staircases than Argo floats are capable of resolving.

4.2 Scale sensitivity of the classifier

One of the key variables not tested by VDB is the vertical spacing of profiles. We took advantage of a high resolution temperature sensor to test the classifier's sensitivity to varying vertical spacing. In addition to a CT sail, SG620 was equipped with a Rockland Scientific microstructure system, including an FP07 fast-response thermistor. The fast-response thermistor sampled at 512 Hz with a response time of ≈ 10 ms, measuring temperature at a spatial resolution of ≈ 1 mm. We binned the temperature profiles at 0.2, 1 and 5 m to test the effect of vertical bin size on the classifier. Each binned value is the median of all samples within the bin. Even at 0.2 m bin size, each bin average is calculated from over 100 measurements. Salinity values were taken from the nearest CT sail measurement, and the classifier picked steps based solely on temperature structure. An example profile at the three binning intervals is shown in Fig. 12. The gaps between adjacent mixed and gradient layers are clear in the 5 m binned profile, as a point cannot be part of both the mixed and gradient layer (Fig. 12b).

When classifying profiles, the three bin sizes give similar results. The differences are most obvious at the upper edge of the staircase zone, where individual steps are smaller (Fig. 12c). The 5 m binned profile completely erases the ≈ 2 m thick steps. The 1 m binned profile also misses the steps, as the ≈ 50 cm thick gradient layers contain at most 1 point. Our classifier requires two points in the gradient layer to classify it. This sets a minimum layer thickness equal to twice the bin size, a limitation shared with VDB's algorithm. A separate issue is apparent with finely binned profiles. Using a smaller bin size, the 40 m thick step around 420 m is excluded (Fig. 12b). This is due to the increased variability introduced by the extra points in the profile, exceeding the maximum allowable temperature variation and causing the step to be discarded. Reconciling these



behaviours will be a challenge for future iterations of the classifier. Perhaps a more sophisticated moving average filter than the simple boxcar used here could smooth out small perturbations in temperature while retaining the sharp shape of the staircases.

245 Considering the total results from all of SG620's dives (Fig. 13) it is clear that finer binning identifies more layers at all depths and of all thicknesses. This is particularly apparent in the upper parts of the pycnocline around 100-200 m. In addition to missing shallow layers, the 5 m binned profiles detect no steps below 500 m, where the temperature changes of the interfaces are smaller. The distribution of density ratio as shown in Fig. 11 is robust to changes in bin size, with a strong peak of thick mixed layers centered around $R_\rho = 1.7$. However, the 5 m binned profiles detected no steps at $R_\rho > 2.5$. This may explain why early studies, with coarser vertical sampling resolution, did not detect any staircases at large values of R_ρ , or in the upper reaches of the pycnocline. This also imposes a limit on the structure detectable from Argo data, which has a minimum detection
250 threshold of 2 dbar (VDB). On bandwidth limited platforms like Argo floats, this issue could be circumvented with on-board processing. Using recorded profiles of temperature and salinity at their maximum resolution, thermohaline staircases could be identified using an algorithm like VDB's algorithm and the location of steps transmitted over a satellite link. This would avoid the need to transmit the high resolution thermohaline profiles while identifying steps at a finer resolution than 2 dbar.

4.3 Limitations of automated classifiers

255 To our knowledge, this is only the second study to use an automated classifier to identify thermohaline staircases, and the first to use one on glider profiles. Early studies with relatively few observations classified staircases manually (Schmitt et al., 1987; Marmorino et al., 1987). Authors sometimes added further detail by classifying staircases as "clean" or "steppy" (Fer et al., 2010). Though more recent work preliminarily identified staircases by threshold gradients e.g. Durante et al. (2019), this was followed by inspection and reclassification by a human operator, again using descriptive labels such as "steppy", "rough" and
260 "slope". Automated classifiers can remove the subjective element from this process, identifying staircases from their physical properties alone in a way that is repeatable and consistent within and between datasets.

The detection of staircases is dependent on the algorithm design and a small number of key parameters, such as maximum allowable density gradient, density variability and thickness of mixed and gradient layers. VDB carried out sensitivity analysis on parameters including maximum mixed layer density gradients, temperature and salinity variability, and gradient layer thick-
265 ness. This analysis showed that VDB's algorithm is most sensitive to changes to the maximum mixed layer density gradient and mostly insensitive to other parameters. Smaller maximum density gradients allow only the sharpest, most clearly defined steps. Larger gradients also identify the less well defined rough steps. VDB did not perform sensitivity analysis on vertical bin size due to the limited nature of Argo profiles which are supplied at 1 dbar resolution. Analysis on the effect of vertical bin size, as described in Sect. 4.2, suggests that this is an important factor in staircase identification.

270 The results from our classifier are robust to changes in the key parameters, and relative differences within the dataset are preserved. However, parameter changes can affect classification of individual profiles. Figure 5 shows the result of three classifications of the same same Argo profile. The first profile is VDB's algorithm on default parameter settings, the second is our classifier using the same parameters, the third is our classifier with the maximum density gradient increased by 4 % and the step height ratio decreased by 10 %. In this example, three rough steps are rejected by our classifier using default

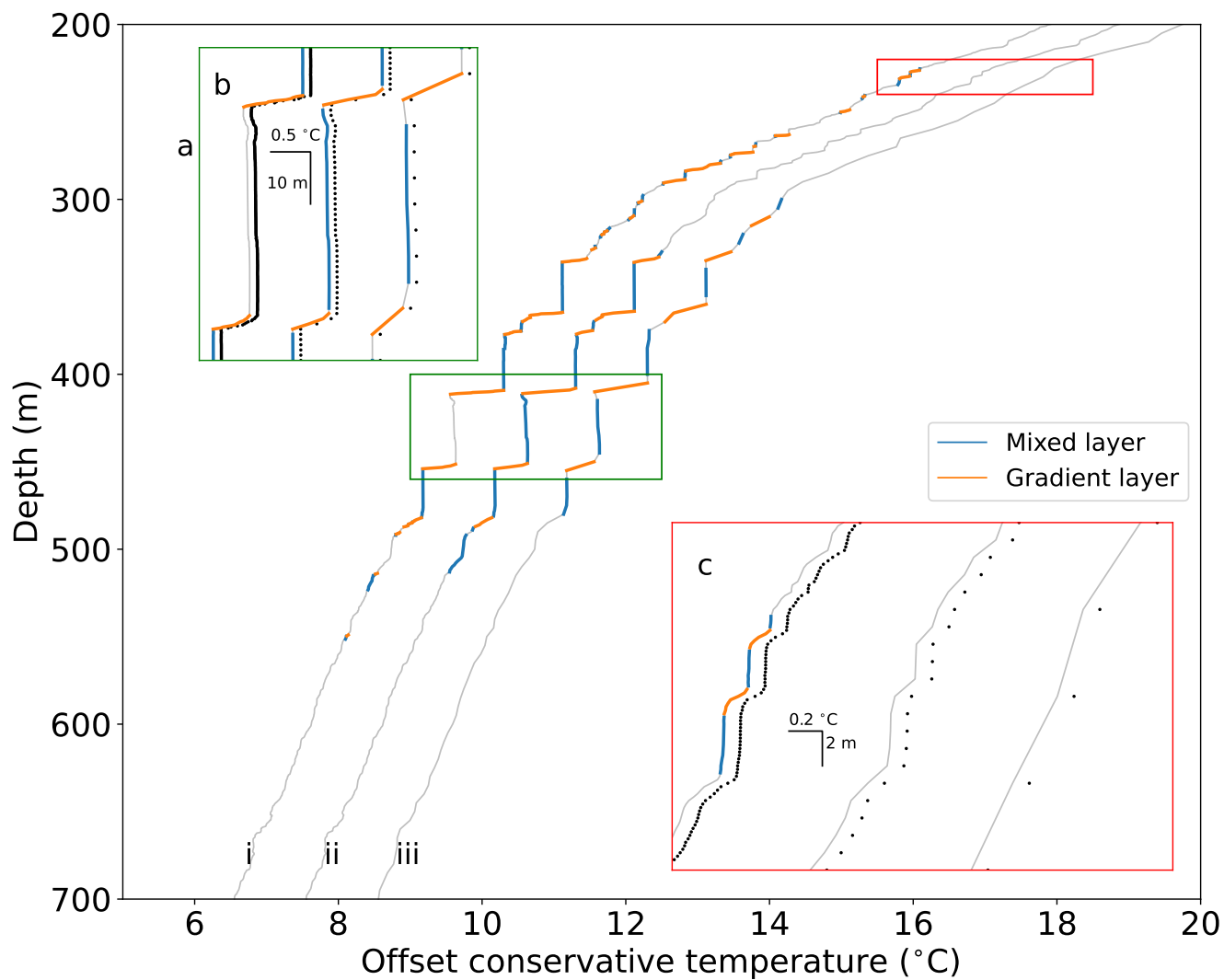


Figure 12. SG620 dive 20 fast-response thermistor temperature. Three profiles are the same data binned at 0.2 m, 1 m and 5 m respectively, then classified. b & c are detailed subsamples of the profiles, offset black dots mark the centers of each depth bin.

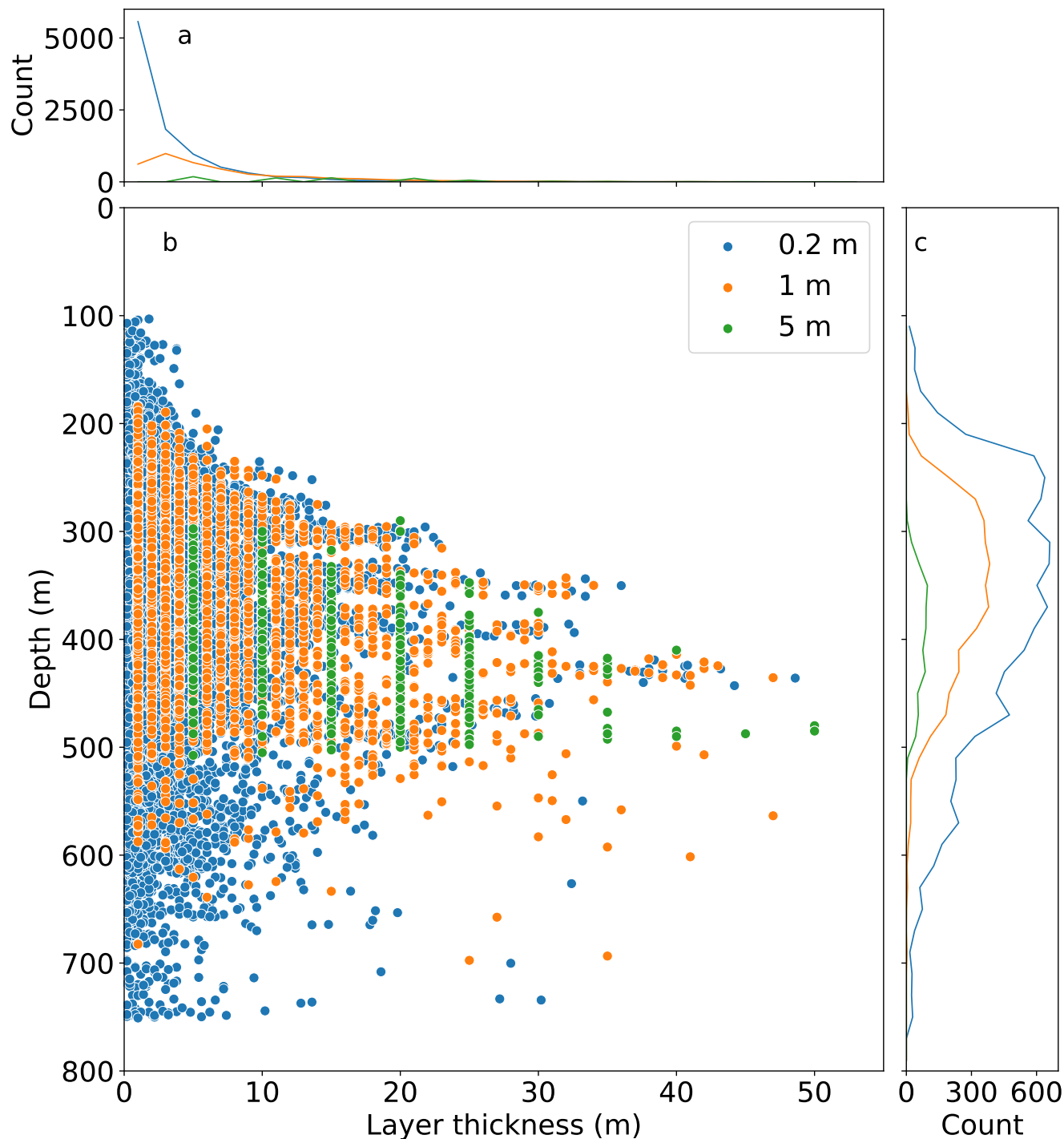


Figure 13. All mixed layers identified from SG620 fast-response thermistor data when binned at 0.2 m, 1 m and 5 m. Lines in a) and c) are binned total number of points in b) with bin widths of 2 m and 20 m respectively.



275 parameters (ii), as the relatively thicker mixed layers exceed the density gradient criterion. By making critical parameters more strict in profile iii, we achieve a closer, but not exactly matching result to VDB's algorithm (Fig. 5). The selection of these key parameters is currently a manual process, guided by previous studies that have established threshold values (Bryden et al., 2014; Timmermans et al., 2008). Once chosen however, key parameters are constant for the whole dataset and the classification of staircases is not altered by the user post-classification. We used the parameter set demonstrated in profile iii for this study.

280 Imperfect data also pose a problem for automated classifiers. In this study, we had to smooth out salinity spikes to prevent false negatives in the classifier (Fig. 7). Small deviations in temperature and salinity that a human classifier would ignore can also cause steps to be rejected (e.g. Durante et al. (2019) Fig. 3). The nine filtering steps in VDB's algorithm and our classifier prevent most false positives, such as the step like structures formed by thermohaline intrusions. However, some visually step like structures are rejected if they fall outside the parameter space (Fig. 13b). At the other extreme, setting key parameters to large values can allow overly lax step classification. This problem is most apparent at greater depths. In the Mediterranean, where staircases extend below 1500 m, individual gradient layers have small magnitude changes in temperature and salinity. These small steps are harder to positively identify, particularly if there is instrument noise in the temperature and salinity profiles. Using VDB's default parameter values on a profile from the Mediterranean, our classifier combines two mixed layers around 1000 dbar (Fig. 5ii). Applying a 4 % decrease in maximum permitted density gradient and a 10 % decrease in step height ratio correctly identifies these as two separate steps (Fig. 5iii). VDB restricted classification to 100-900 dbar, so the performance of VDB's algorithm at this depth is unknown. Future classifiers could resolve the issue of identifying steps of smaller magnitude in deeper water by using varying parameters, perhaps scaling the threshold values for step identification by the background gradients in temperature, salinity and density.

295 Automated classifiers for thermohaline staircases are in their infancy. We hope that the example created by VDB and built on by this manuscript can be further improved, and that other classifiers may be created to resolve issues raised in this section. We have made our classifier available on GitHub, with full development history, software tests, sample data and a demonstration notebook (Rollo, 2021a). Future work on thermohaline classifiers, and many other code intensive oceanographic projects, could benefit from the iterative, collaborative approach of open source software development enabled by platforms like this.

5 Summary

300 Building on the work of VDB we developed a classifier to detect thermohaline staircases. This improved classifier can operate on datasets at any regular vertical spacing. The classifier can also be used on datasets with suboptimal salinity data, such as profiles contaminated by salinity spikes, or salinity measured at lower spatial resolution e.g. when using a fast-response thermistor. We used this classifier to successfully identify two periods of strong thermohaline staircasing in the tropical North Atlantic. Our classifier is flexible, extensible and designed to be simple to use.

305 Based on our observations of thermohaline staircases, we hypothesise that strong vertical gradients in temperature and salinity inhibit the formation of staircases in locations where the density ratio is favourable to their formation. Implementation



of this result could improve model sub-grid parametrisation of diapycnal mixing in regions such as the tropical North Atlantic and Mediterranean, where thermohaline staircases are widespread and long-lived.

310 Using fast-response thermistor data, combined with salinity observations, we were able to classify staircases at the sub metre scale. This is a promising demonstration of automated classification at smaller scales, which can be useful in areas such as the Arctic where small scale thermohaline staircases are known to form.

Code and data availability. Thermohaline classifier code is archived at Rollo (2021a). Glider data are held at the British Oceanographic Data Centre (Rollo, 2021b).

315 *Author contributions.* RAH, KJH and CR contributed to the design of the experiment and data collection. CR created the algorithm and produced the figures. CR prepared the manuscript with contributions from KJH and RAH.

Competing interests. The authors declare that they have no conflict of interest.

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